Inverse Problems for Scanning Magnetic Microscopy

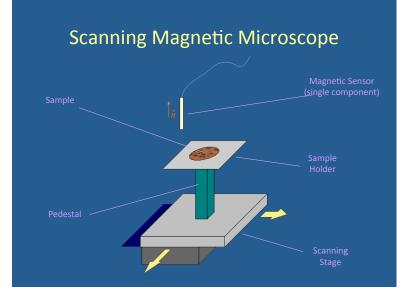
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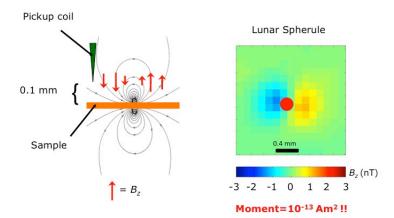
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Bridging the Gap Workshop, Princeton, October 1-2, 2012



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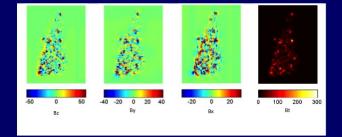
What the SQUID Microscope Measures



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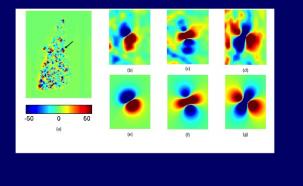
Allende Meteorite





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Dipolar Features in Allende



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Constitutive Relations

- ► Given a quasi-static **R**³-valued magnetization **M**,
- ▶ the magnetic-flux density **B** and the magnetic field **H** satisfy

$$\mathbf{B} = \mu_0 (\mathbf{H} + \mathbf{M}). \tag{1}$$

- Maxwell's equations give $\nabla \times \mathbf{H} = \mathbf{0}$ and $\nabla \cdot \mathbf{B} = 0$.
- Hence H = −∇φ where φ is the magnetic scalar potential, and taking divergence in (1)

$$\Delta \phi = \boldsymbol{\nabla} \cdot \mathbf{M} \tag{2}$$

Potentials and Magnetizations

which can be recast in the form

$$\phi(\mathbf{r}) = \frac{1}{4\pi} \iiint \frac{\mathbf{M}(\mathbf{r}') \cdot (\mathbf{r} - \mathbf{r}')}{|\mathbf{r} - \mathbf{r}'|^3} \, d\mathbf{r}', \quad \mathbf{r} \notin \text{supp } \mathbf{M}.$$
(3)

SCA: Assume support of M is a distribution of the form

$$\mathbf{M}(\mathbf{x},z) = \mathbf{m}(\mathbf{x})\delta_0(z) =: (\mathbf{m}_T(\mathbf{x}), m_3(\mathbf{x}))\delta_0(z),$$

where $\mathbf{m}_T = (m_1, m_2)$ and $m_1, m_2, m_3 \in L^p(\mathbf{R}^2)$. Then

$$\phi(\mathbf{x},z) = \frac{1}{4\pi} \iint \left(\frac{\mathbf{m}_{\mathcal{T}}(\mathbf{x}') \cdot (\mathbf{x} - \mathbf{x}')}{(|\mathbf{x} - \mathbf{x}'|^2 + z^2)^{3/2}} + \frac{m_3(\mathbf{x}')z}{(|\mathbf{x} - \mathbf{x}'|^2 + z^2)^{3/2}} \right) d\mathbf{x}'$$

for all (\mathbf{x}, z) such that either $z \neq 0$ or $\mathbf{x} \notin$ supp. **m**.

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Thin plate potentials as convolutions

Then

$$\phi(\mathbf{x}, z) = \frac{1}{2} \left(\mathbf{H}_{z} * \mathbf{m}_{T}(\mathbf{x}) + P_{z} * m_{3}(\mathbf{x}) \right)$$

= $\frac{1}{2} P_{|z|} * \left(R_{1}(m_{1}) + R_{2}(m_{2}) + \frac{z}{|z|} m_{3} \right) (\mathbf{x}),$

where

$$P_z(\mathbf{x}) := \frac{1}{2\pi} \frac{z}{(|\mathbf{x}|^2 + z^2)^{3/2}}, \quad \mathbf{H}_z(\mathbf{x}) := \frac{1}{2\pi} \frac{\mathbf{x}}{(|\mathbf{x}|^2 + z^2)^{3/2}}$$

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and R_1 and R_2 are *Riesz transforms*.

Riesz transforms

For f ∈ L^p(R²), p ∈ (1,∞), the Riesz transforms of f, denoted by R₁(f) and R₂(f), are defined by

$$R_j(f)(\mathbf{x}) := \lim_{\epsilon \to 0} \frac{1}{2\pi} \iint_{\mathbf{R}^2 \setminus B(\mathbf{x},\epsilon)} f(\mathbf{x}') \frac{(x_j - x_j')}{|\mathbf{x} - \mathbf{x}'|^3} \, d\mathbf{x}'.$$
(4)

- The limit (4) exists a.e. and R_j continuously maps L^p(R²) into itself.
- ▶ In the Fourier domain $\widehat{R_j f}(\kappa) = -i \frac{\kappa_j}{|\kappa|} \widehat{f}(\kappa)$.

Silent sources

- A magnetization m is silent from above (resp. below) if it is equivalent from above (resp. below) to the null magnetization. It is silent if it is silent from above and below.
- Since the Poisson transform is injective, the magnetization **m** is silent from above if and only if $R_1(m_1) + R_2(m_2) + m_3 = 0$ and silent from below if and only if $R_1(m_1) + R_2(m_2) m_3 = 0$.
- ▶ Hence, **m** is silent if and only if $R_1(m_1) + R_2(m_2) = 0$ and $m_3 = 0$, i.e., if and only if $m_3 = 0$ and \mathbf{m}_T is divergence free.

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The Hardy-Hodge decomposition Let

 $H^+ := \{(R_1(f), R_2(f), f) : f \in L^p\}$ and $H^- := \{(-R_1(f), -R_2(f), f) : f\}$

Theorem

For p > 1, we have the following direct sum:

$$\left(L^{p}(\mathbf{R}^{2})\right)^{3}=H^{+}\oplus H^{-}\oplus \mathrm{S}.$$

The sum is orthogonal sum when p = 2. Specifically, $\mathbf{m} = (m_1, m_2, m_3) = P_{H^+}(\mathbf{m}) + P_{H^-}(\mathbf{m}) + P_{\mathrm{S}}(\mathbf{m})$, where

$$P_{H^{+}}(\mathbf{m}) = \left(R_{1}(m^{+}), R_{2}(m^{+}), m^{+}\right), \quad 2m^{+} := -\Sigma_{j=1}^{2}R_{j}(m_{j}) + m_{3}$$

$$P_{H^{-}}(\mathbf{m}) = \left(-R_{1}(m^{-}), -R_{2}(m^{-}), m^{-}\right), \quad 2m^{-} := \Sigma_{j=1}^{2}R_{j}(m_{j}) + m_{3}$$

$$P_{S}(\mathbf{m}) = \left(-R_{2}(d), R_{1}(d), 0\right), \quad d := R_{2}(m_{1}) - R_{1}(m_{2}).$$

Equivalence via Hardy-Hodge decomposition

Theorem

Let $\mathbf{m} \in (L^p(\mathbf{R}^2))^3$.

- ► The magnetization **m** is silent from above (resp. below) if and only if P_{H⁻}(**m**) = 0 (resp. P_{H⁺}(**m**) = 0).
- ► The magnetization **m** is silent from above and below if and only if it belongs to S; that is, if and only if **m**_T is divergence-free and m₃ = 0.
- If supp m ≠ R², then m is silent from above if and only if it is silent from below.

Unidirectional Magnetizations

A magnetization m is *unidirectional* if m = Qu for some fixed u ∈ R³ and some Q ∈ L^p(R²).

 Unidirectional magnetizations occur naturally for materials formed in a uniform external magnetic field.

Unidirectional Magnetizations

Theorem

- A unidirectional magnetization m ∈ (L^p(R²))³ is determined uniquely by its direction and the field it generates from above (or below). In particular, m is silent from above (or below) if, and only if m = 0.
- For u = (u₁, u₂, u₃) ∈ R³ with u₃ ≠ 0, any magnetization in (L^p(R²))³ is equivalent from above to a unidirectional magnetization of the form Q(x)u.
- ► A compactly supported unidirectional magnetization is equivalent from above (or below) to no other compactly supported unidirectional magnetization.

Compactly supported bidirectional silent sources

Theorem

Suppose $\mathbf{m}(\mathbf{x}) = Q(\mathbf{x})\mathbf{u} + R(\mathbf{x})\mathbf{v}$ where $\mathbf{u} = (u_1, u_2, u_3)$ and $\mathbf{v} = (v_1, v_2, v_3)$ are nonzero vectors in \mathbf{R}^3 while Q, R are distributions with compact support.

 If u₃ or v₃ is nonzero, then m is silent iff m = 0.
 If u₃ = v₃ = 0, then m is silent iff m_T(x) = Q(x)(u₁, u₂) + R(x)(v₁, v₂) is divergence free.



L-R: Ed Saff, Ben Weiss, Laurent Baratchart, Doug Hardin at Ben and Eduardo's (taking the picture) lab at MIT.

GeoMath Wish List

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GeoMath Wish List

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Summary: Generating good point sets

- Given: a *d*-rectifiable set A with H_d(A) > 0 that is contained in a *d*-regular set and a positive and continuous density ρ(x) on A.
- To distribute points on A according to ρ , choose s > d and

 $w(x,y) := \left(\rho(x)\rho(y)\right)^{-s/2d},$

Compute configurations that (nearly) minimizes the weighted s-energy:

$$E_{s}^{w}(\{x_{1}, x_{2}, ..., x_{N}\}) := \sum_{i=1}^{N} \sum_{j=1 \atop j \neq i}^{N} \frac{w(x_{i}, x_{j})}{|x_{i} - x_{j}|^{s}}$$

Any sequence of such configurations will have limiting distribution ρ and is quasi-uniform.

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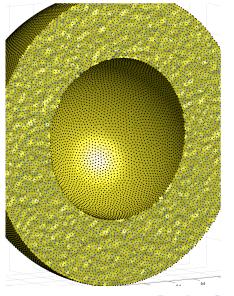
Compute configurations that (nearly) minimizes the weighted s-energy:

$$E_s^w(\omega_N) := \sum_{i=1}^N \sum_{j=1\atop{j\neq i}}^N \frac{w(x_i, x_j)}{|x_i - x_j|^s} \Phi(\frac{|x_i - x_j|}{r_N})$$

Any sequence of such configurations will have limiting distribution ρ and is quasi-uniform.

Spherical Shell - for geoscience models

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500K points in spherical shell .55 < r < 1, 'low' s = 3.5 energy
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