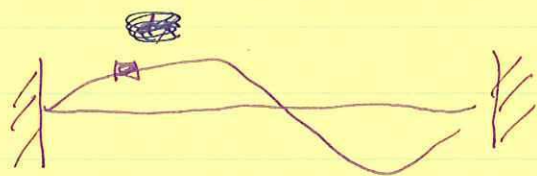
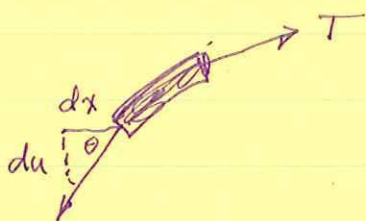


Violin string: tension  $T$ , density  $\rho(x)$



$u(x,t)$  only in  $y$  direction



$$\tan \theta \approx \sin \theta = \frac{\partial u}{\partial x}$$

restoring force  $T [\tan \theta(x+dx) - \tan \theta(x)]$

$$\approx T \left[ \frac{\partial u}{\partial x}(x+dx) - \frac{\partial u}{\partial x}(x) \right]$$

Newton's law:  $F = ma$

$$\rho(x) \frac{\partial^2 u}{\partial t^2} = T \left[ \frac{\frac{\partial u}{\partial x}(x+dx) - \frac{\partial u}{\partial x}(x)}{dx} \right]$$

$$\rho(x) \frac{\partial^2 u}{\partial t^2} = T \frac{\partial^2 u}{\partial x^2}$$

fixed ends  $u(0,t) = u(L,t) = 0$

Multiply by velocity  $\frac{\partial u}{\partial t}$  and  $\int_0^L dx$

$$\text{lhs} = \int_0^L \rho \frac{\partial^2 u}{\partial t^2} \frac{\partial u}{\partial t} dx = \frac{d}{dt} \frac{1}{2} \int_0^L \rho \left( \frac{\partial u}{\partial t} \right)^2 dx$$

rhs by parts

$$T \int_0^L \partial_x^2 u \partial_t u \, dx = T \left[ \cancel{\partial_x u \partial_t u} \right]_0^L$$

$$- T \int_0^L \partial_x u \frac{d}{dt} (\partial_x u) \, dx$$

$$= - \frac{d}{dt} \frac{1}{2} \int_0^L T (\partial_x u)^2 \, dx$$

$$\frac{d}{dt} \int_0^L \left[ \frac{1}{2} \rho (\partial_t u)^2 + \frac{1}{2} T (\partial_x u)^2 \right] dx = 0$$

~~conservation~~ conservation of energy

$\frac{1}{2} \rho (\partial_t u)^2$  : ke density

$\frac{1}{2} T (\partial_x u)^2$  : pe density

Hamilton's principle :

$$I = \int_{t_1}^{t_2} \int_0^L L(u, \partial_t u, \partial_x u) \, dx \, dt$$

$$\delta I = 0 \quad L = \frac{1}{2} \rho (\partial_t u)^2 - \frac{1}{2} T (\partial_x u)^2$$

$$I = \int_{t_1}^{t_2} \int_0^L \left[ \frac{1}{2} \rho (\partial_t u)^2 - \frac{1}{2} T (\partial_x u)^2 \right] dx \, dt$$

$$\delta I = \delta \int_{t_1}^{t_2} dt \int_0^L L(u, \partial_t u, \partial_x u) \, dx$$

$$= \int_{t_1}^{t_2} dt \int_0^L \left( \frac{\partial L}{\partial u} \delta u + \frac{\partial L}{\partial (\partial_t u)} \partial_t \delta u + \frac{\partial L}{\partial (\partial_x u)} \partial_x \delta u \right) dx$$

$$\begin{aligned}
 &= \int_0^L \left[ \frac{\partial L}{\partial(\partial_t u)} \delta u \right]_{t_1}^{t_2} dx \quad \rightarrow 0 \text{ since } u(x, t_1) \text{ and } u(x, t_2) \text{ fixed} \\
 &+ \int_{t_1}^{t_2} \left[ \frac{\partial L}{\partial(\partial_x u)} \delta u \right]_0^L dt \quad \rightarrow 0 \text{ see below} \\
 &+ \int_{t_1}^{t_2} dt \int_0^L \delta u \left[ \frac{\partial L}{\partial u} - \frac{\partial}{\partial t} \left( \frac{\partial L}{\partial(\partial_t u)} \right) - \frac{\partial}{\partial x} \left( \frac{\partial L}{\partial(\partial_x u)} \right) \right] dx
 \end{aligned}$$

~~fixed bc~~

natural bc is  $\frac{\partial L}{\partial(\partial_x u)} = T(\partial_x u) = 0$  for ends

instead we must impose an admissibility constraint upon  $\delta u$ : namely  $\delta u(0, t) = \delta u(L, t) = 0$

Then  $\Gamma$  ~~is~~ stationary for arbitrary admissible  $\delta u$  iff

$$\frac{\partial L}{\partial u} - \frac{\partial}{\partial t} \left( \frac{\partial L}{\partial(\partial_t u)} \right) - \frac{\partial}{\partial x} \left( \frac{\partial L}{\partial(\partial_x u)} \right) = 0$$

zero in our case

$$p \partial_t^2 u - T \partial_x^2 u = 0$$

Normal mode solutions:  $u(x, t) = u(x) e^{i\omega t}$   
 $\uparrow$  eigen-fun: mode shape  $\uparrow$  eigen-freq

comment on FT

convention  $\neq$  Aki & Richards



$$-T \frac{d^2 u}{dx^2} = \rho \omega^2 u \quad \text{with } u(0) = u(L) = 0$$

eigenvalue problem,  $\rho > 0$  analogous to  $\pi$  for-def.

be inner product

$$\langle u, u' \rangle = \int_0^L \rho(x) u(x) u'(x) dx$$

Rewrite as

$$-\rho^{-1} T \frac{d^2 u}{dx^2} = \omega^2 u, \quad H = -\rho^{-1} T \frac{d^2}{dx^2}$$

operator  $H = -\rho^{-1} T \frac{d^2}{dx^2}$  Hermitian w.r.t.  $\langle, \rangle$

Proof easy: 2 integrations by parts

$$\begin{aligned} \langle u, \overset{H}{-\rho^{-1} T \frac{d^2}{dx^2} u'} \rangle &= -T \int_0^L u \frac{d^2 u'}{dx^2} dx \\ &= -T \left[ u \frac{du'}{dx} \right]_0^L + T \int_0^L \frac{du}{dx} \frac{du'}{dx} dx \\ &\quad \left\{ \begin{array}{l} \text{zero by bc.} \\ \text{ditto} \end{array} \right. \\ &= T \left[ \frac{du}{dx} u' \right]_0^L - T \int_0^L \frac{d^2 u}{dx^2} u' dx \\ &= \langle \overset{H}{-\rho^{-1} T \frac{d^2}{dx^2} u}, u' \rangle \quad \text{qed} \end{aligned}$$

intimately involves bc — typical of field theories

Now easy to show that  $\omega^2$  real and

$$(\omega^2 - \omega'^2) \langle u, u' \rangle = (\omega^2 - \omega'^2) \int_0^L \rho u u' dx = 0$$

orthogonality end here class #2

intimate association: Hermitian, real eigenvalues, energy conservation

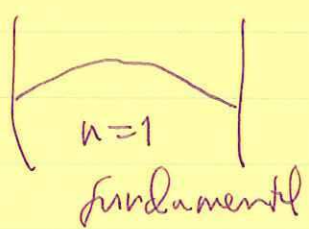
Example:  $\rho(x) = \rho$ , homogeneous

$$-(T/\rho) \frac{d^2 u}{dx^2} = \omega^2 u, \quad u(0) = u(L) = 0$$

$$\omega_n = \frac{n\pi}{L} \sqrt{T/\rho}$$

$$u_n(x) = \sqrt{\frac{2}{\rho L}} \sin\left(\frac{n\pi x}{L}\right)$$

}  $n = 1, 2, \dots$



first overtone at twice frequency

orthogonality  $\frac{2}{L} \int_0^L \sin \frac{n\pi x}{L} \sin \frac{m\pi x}{L} dx = \delta_{nm}$

$$\langle u_n, u_m \rangle = \delta_{nm}$$

Class #3

Humb's question — when ~~is~~ is it useful to seek normal mode solutions?

$$\rho(x) \frac{d^2 u}{dt^2} = T \frac{d^2 u}{dx^2}$$

b.c.  $u(0,t) = u(l,t) = 0$

Instead seek a separable solution

$$u(x,t) = f(x)g(t)$$

$$\rho f \frac{d^2 g}{dt^2} = T g \frac{d^2 f}{dx^2}$$

$$\underbrace{\frac{1}{Tg} \frac{d^2 g}{dt^2}}_{\text{fcn of } t \text{ only}} = \underbrace{\frac{1}{\rho f} \frac{d^2 f}{dx^2}}_{\text{fcn of } x \text{ only}}$$

⇒ must both be = to a constant, which we call  $-\omega^2/T$

$$\frac{1}{g} \frac{d^2 g}{dt^2} = -\omega^2 = \frac{T}{\rho} \frac{1}{f} \frac{d^2 f}{dx^2}$$

⇒  $g \sim e^{i\omega t}$        $T \frac{d^2 f}{dx^2} = -\rho \omega^2 f$

But what if  $T = T(t)$ : tuning your violin while you play it.



Then  $\frac{1}{T(t)} \frac{1}{y} \frac{d^2 y}{dt^2} = \text{const} = \frac{1}{\rho(x)} \frac{1}{f} \frac{d^2 f}{dx^2}$

In general it is permissible to seek normal mode solutions whenever none of the parameters describing the system or model depend on ~~the~~ time

In the discrete case

$$T \ddot{q} + V q = 0$$

ke: ~~T~~  $T = \frac{1}{2} \dot{q}^T T \dot{q}$

pe:  $V = V_0 + \frac{1}{2} q^T V q$

$T$  and  $V$  are time-independent

This is the hallmark of a conservative system.

Then do homogeneous string

4<sup>th</sup> lecture: Thurs Feb 15

tensors of multilinear functionals  
taken from mimeographed notes  
plus Appendix A of D & T.



5th class : 20 Feb

linear functional  $f(\underline{v}) \rightarrow \text{scalars}$   
isomorphic to vectors  $\uparrow$  slot  
 $f(\underline{v}) = \underline{f} \cdot \underline{v}$  for all  $\underline{v}$

multilinear functional  $T(\underline{u}, \underline{v})$

tensor product :  $TS(\underline{u}, \underline{v}, \underline{x}, \underline{y})$   
 $= T(\underline{u}, \underline{v})S(\underline{x}, \underline{y})$  order  $p+q$

write without  $\otimes$   $T \otimes S$

trace  $\text{tr} T = T(\hat{x}_i, \hat{x}_i) = T(\hat{x}'_i, \hat{x}'_i)$

transpose  $T^T(\underline{u}, \underline{v}) = T(\underline{v}, \underline{u})$

components  $T_{ij} = T(\hat{x}_i, \hat{x}_j)$   
just like  $f_i = \underline{f} \cdot \hat{x}_i = f(\hat{x}_i)$

$\hat{x}_i \dots \hat{x}_q$  a basis for space  
of tensors of order  $q$  -  
dimension  $3^q$

e.g. ~~the~~  $T = T_{ij} \hat{x}_i \hat{x}_j$

$(TS)_{ijkl} = T_{ij} S_{kl}$

$\text{tr} T = T_{ii}$

identity tensor  $\underline{I}(\underline{u}, \underline{v}) = \underline{u} \cdot \underline{v}$   
 $I_{ij} = \delta_{ij}$ , isotropic tensor

alternating tensor  $\Lambda(\underline{u}, \underline{v}, \underline{w}) = \underline{u} \cdot (\underline{v} \times \underline{w})$

$$\Lambda_{ijk} = \pm \epsilon_{ijk} \quad \begin{array}{l} \text{rt handed} \\ \text{left handed} \end{array}$$

Most general isotropic tensor  $a \underline{I}$ ,  $a \delta_{ij}$

change of basis:  $T_{ij}' = (\hat{x}_i' \cdot \hat{x}_j) (\hat{x}_j' \cdot \hat{x}_i) T_{ik}$

Then: tensors of order  $q=2$  as linear operators

End with physical examples of tensors. Common in linear constitutive relations

Ohm's law:  $\underline{J} = \underline{\sigma} \cdot \underline{E}$

thermal conductivity:  $\underline{H} = -\underline{K} \cdot \nabla \theta$

dielectric tensor:  $\underline{D} = \underline{\epsilon} \cdot \underline{E}$

inertia tensor:  $\underline{L} = \underline{I} \cdot \underline{\omega}$

stress tensor:  ~~$\underline{\sigma} = \underline{T} \cdot \underline{n}$~~

$$\begin{array}{c} \Delta A \\ \times \hat{n} \\ + \hat{n} \end{array} \quad \underline{f} = (\hat{n} \Delta A) \cdot \underline{T}$$

or since  $\underline{T} = \underline{T}^T$

$$\underline{f} = \underline{T} \cdot (\hat{n} \Delta A)$$

