

Shrinking Ice Sheets, Rising Sea Level

Today and in the Last InterGlacial

Frederik J Simons

Princeton University

Robert E. Kopp

Rutgers University

Chris T. Harig

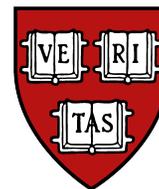
University of Arizona

Adam C. Maloof Michael O. Oppenheimer

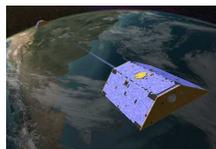
Princeton University

Jerry X. Mitrovica

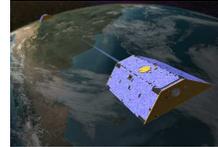
Harvard University



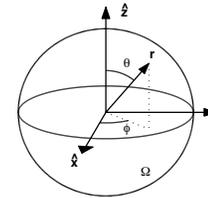
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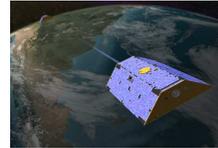
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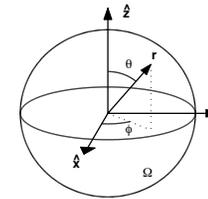
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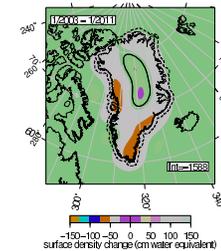
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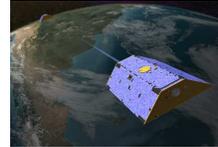
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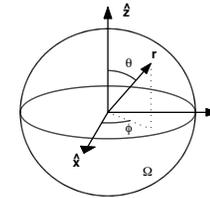
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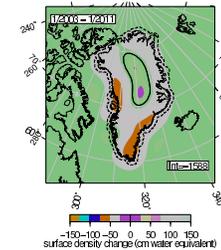
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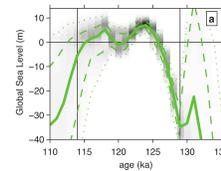
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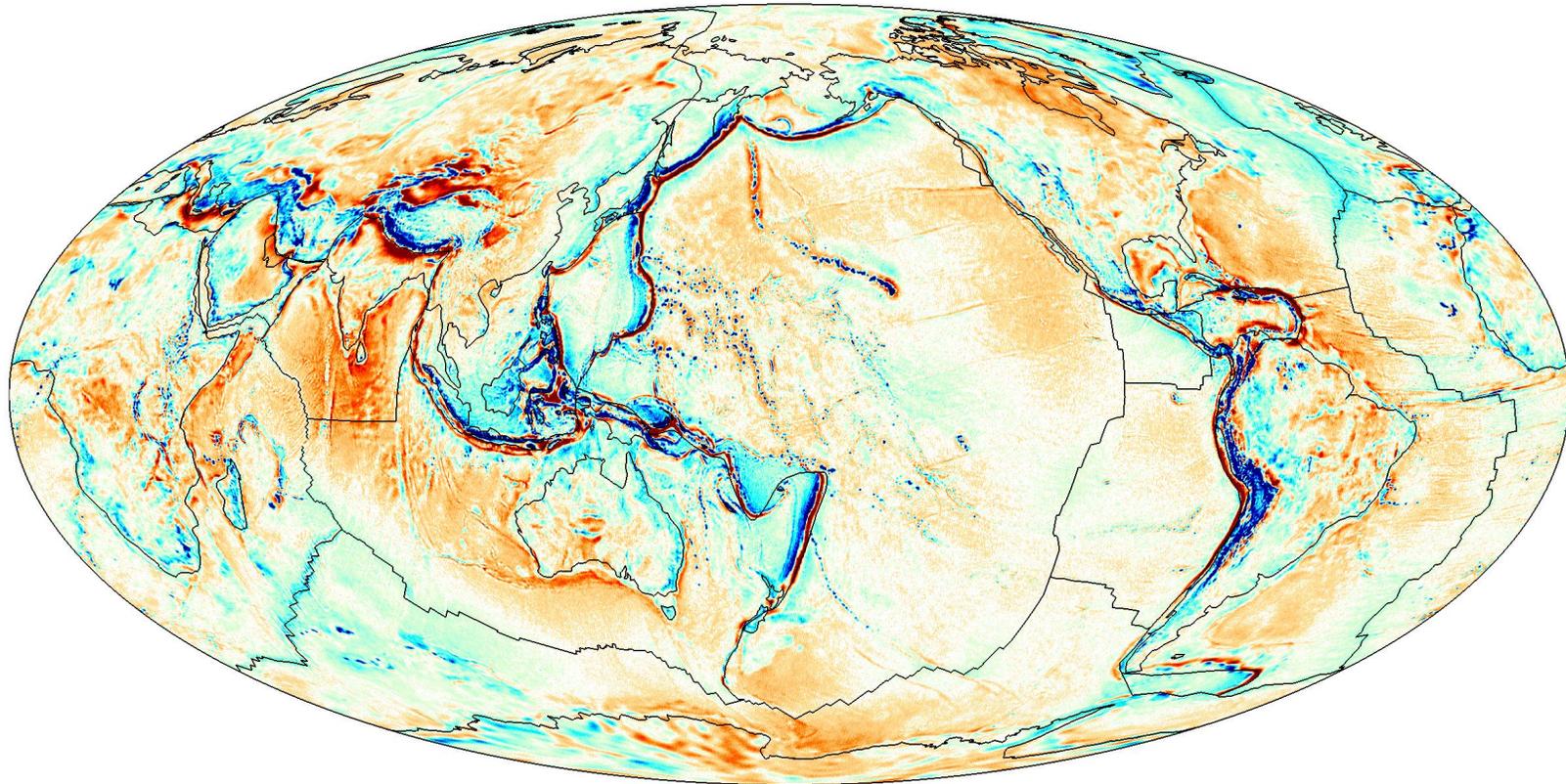


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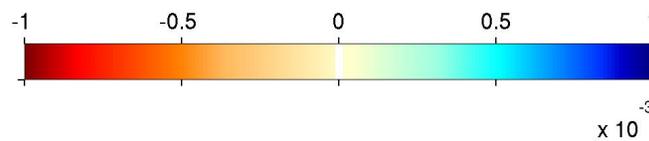


Earth's gravity field is highly variable...

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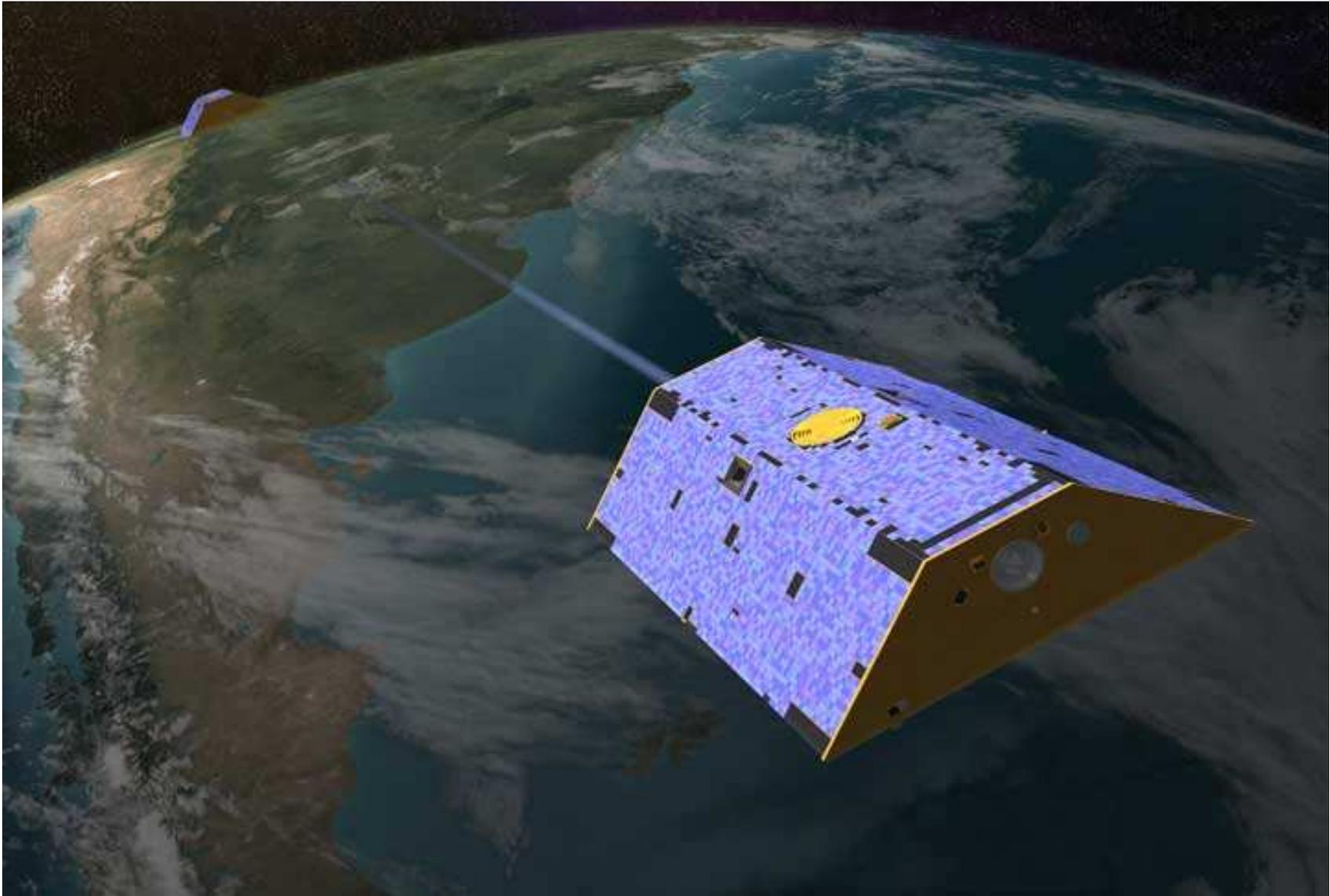


EGM2008 free-air anomaly to L = 1500 with respect to WGS84 [m/s^2]



$[\pm 1] \times 10^{-3}$

...and it changes over time



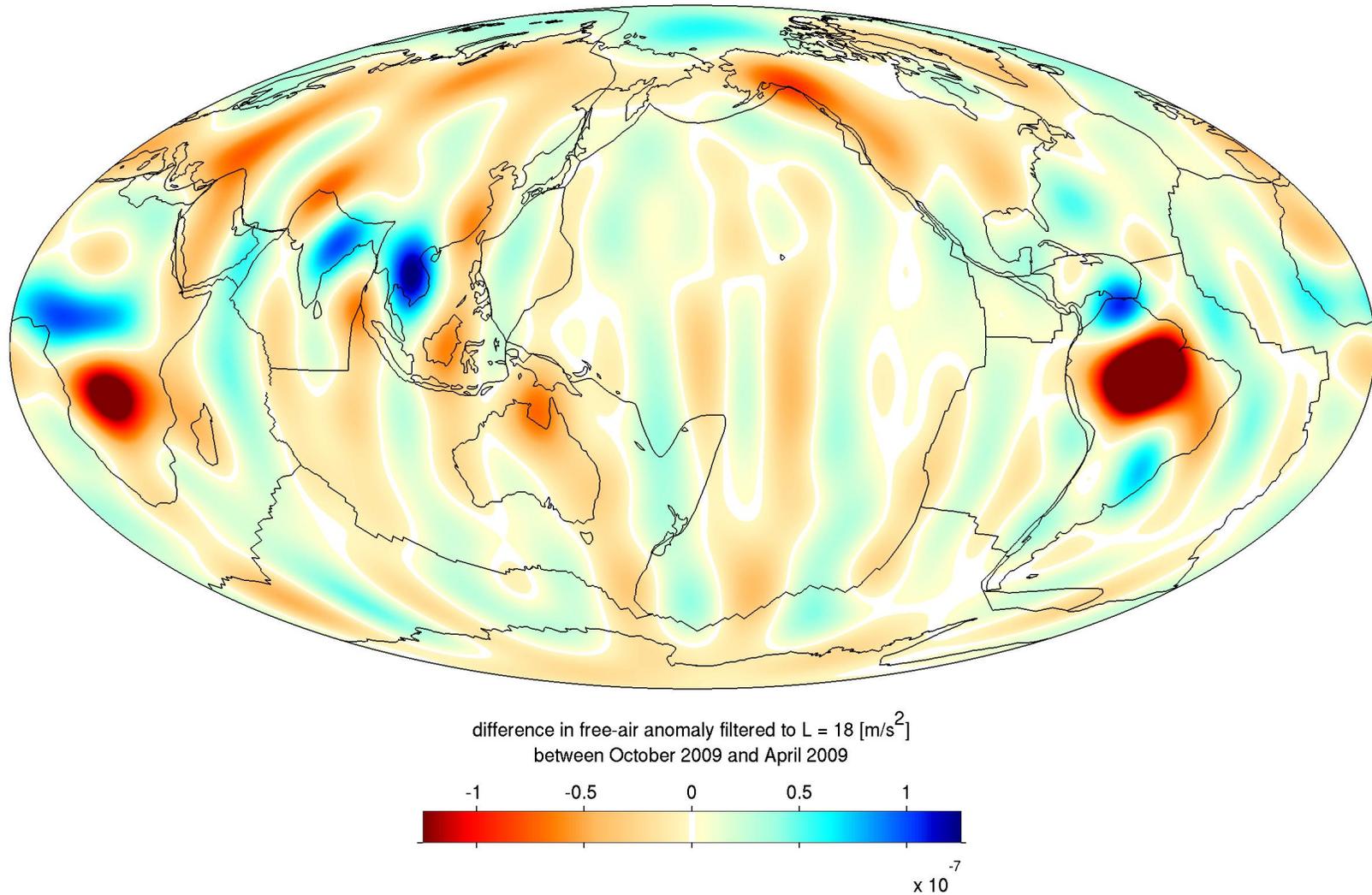
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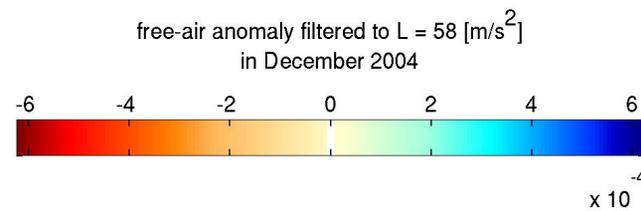
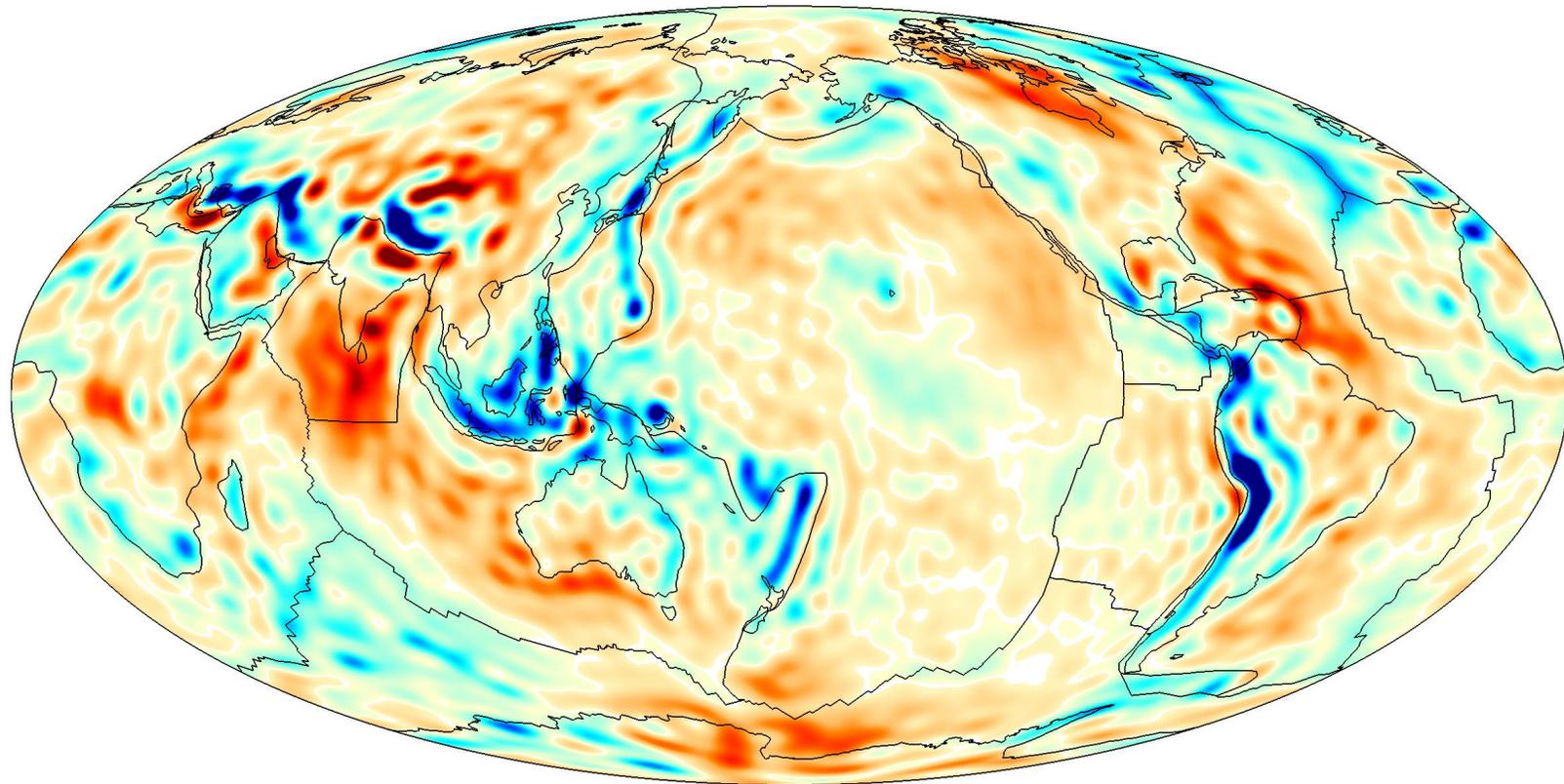
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 - **The question is, of course:**
with what *spatial, temporal, and spectral* resolution?
-

The hydrological signal is big and large

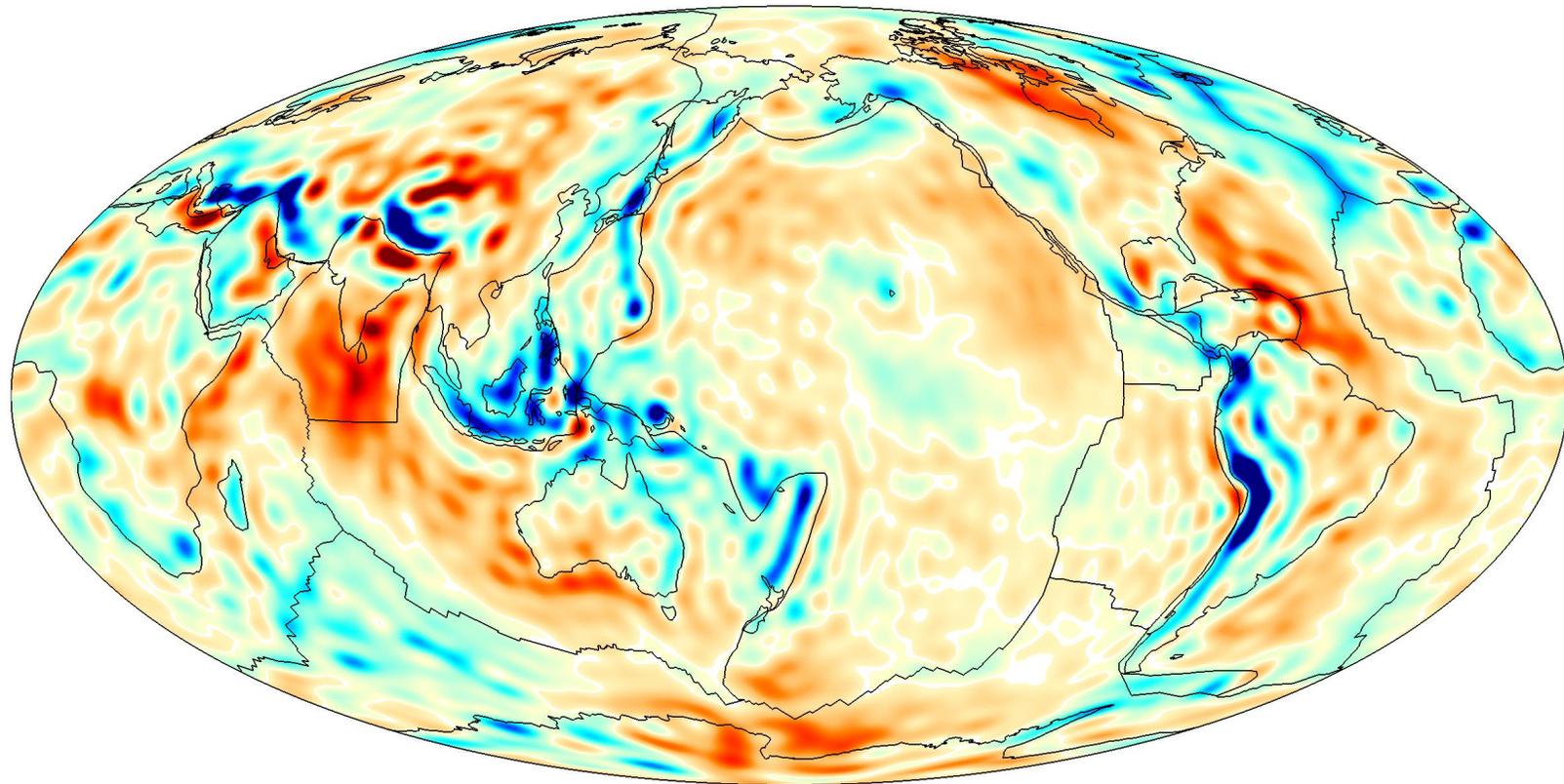


What lurks in the high-frequency “noise”? – 1

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What lurks in the high-frequency “noise”? – 2

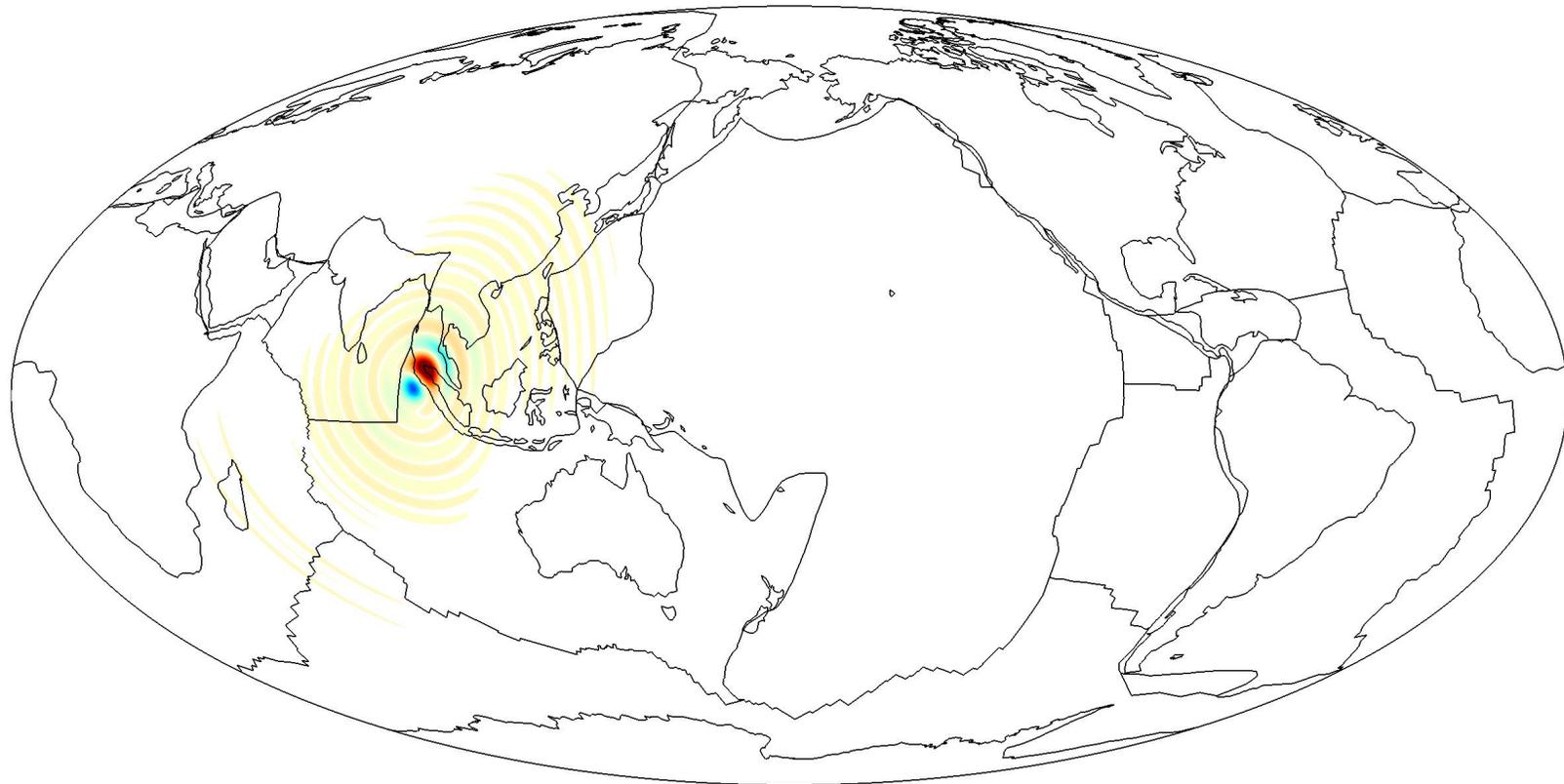


free-air anomaly filtered to $L = 58 \text{ [m/s}^2\text{]}$
in January 2005

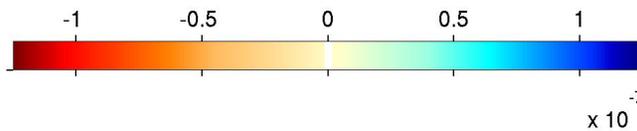
-6 -4 -2 0 2 4 6

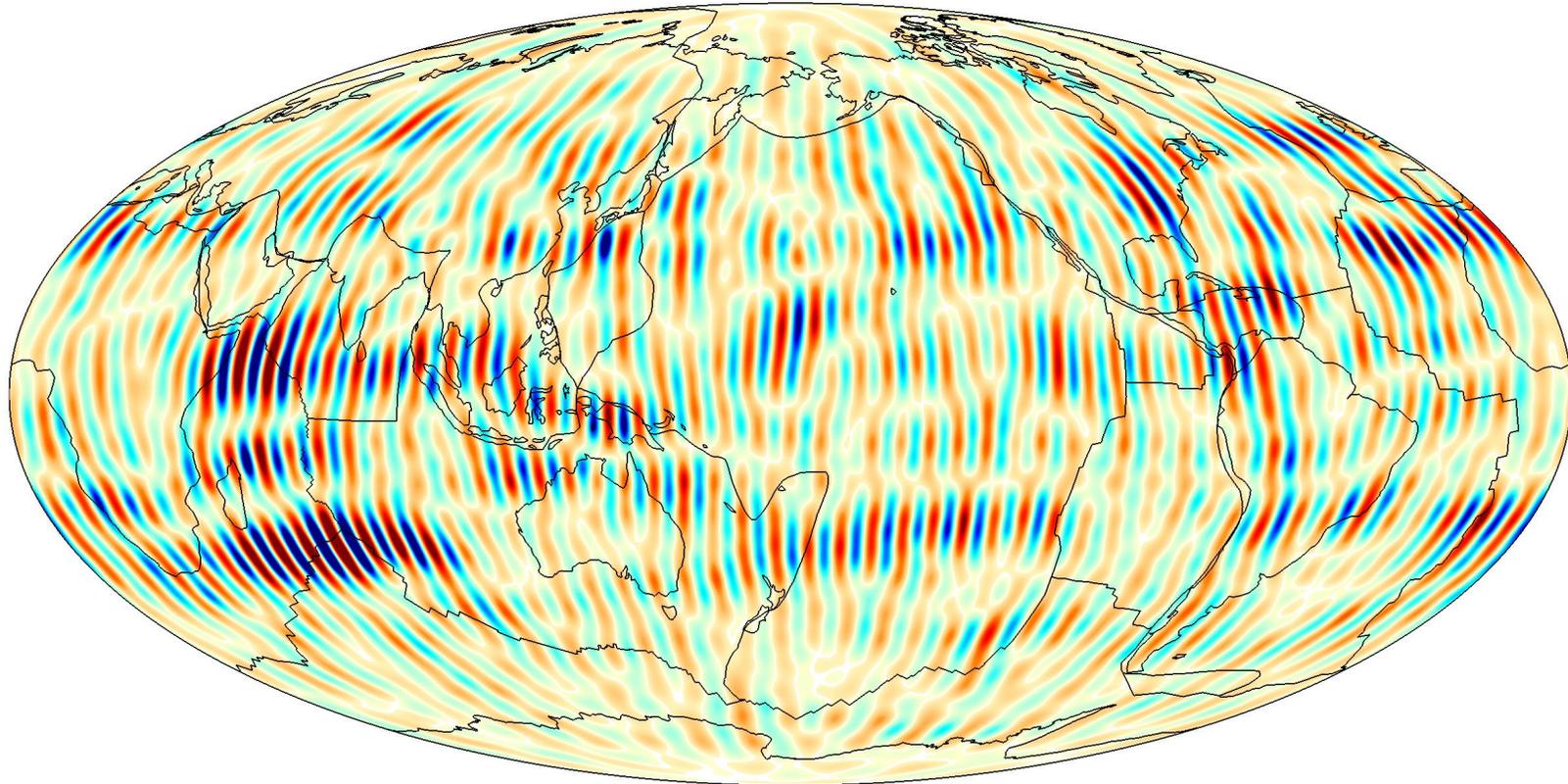
$\times 10^{-4}$

Earthquakes are small (even large ones)

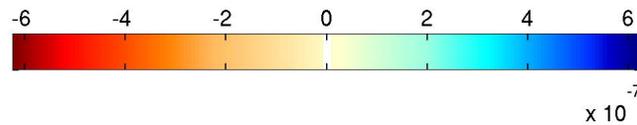


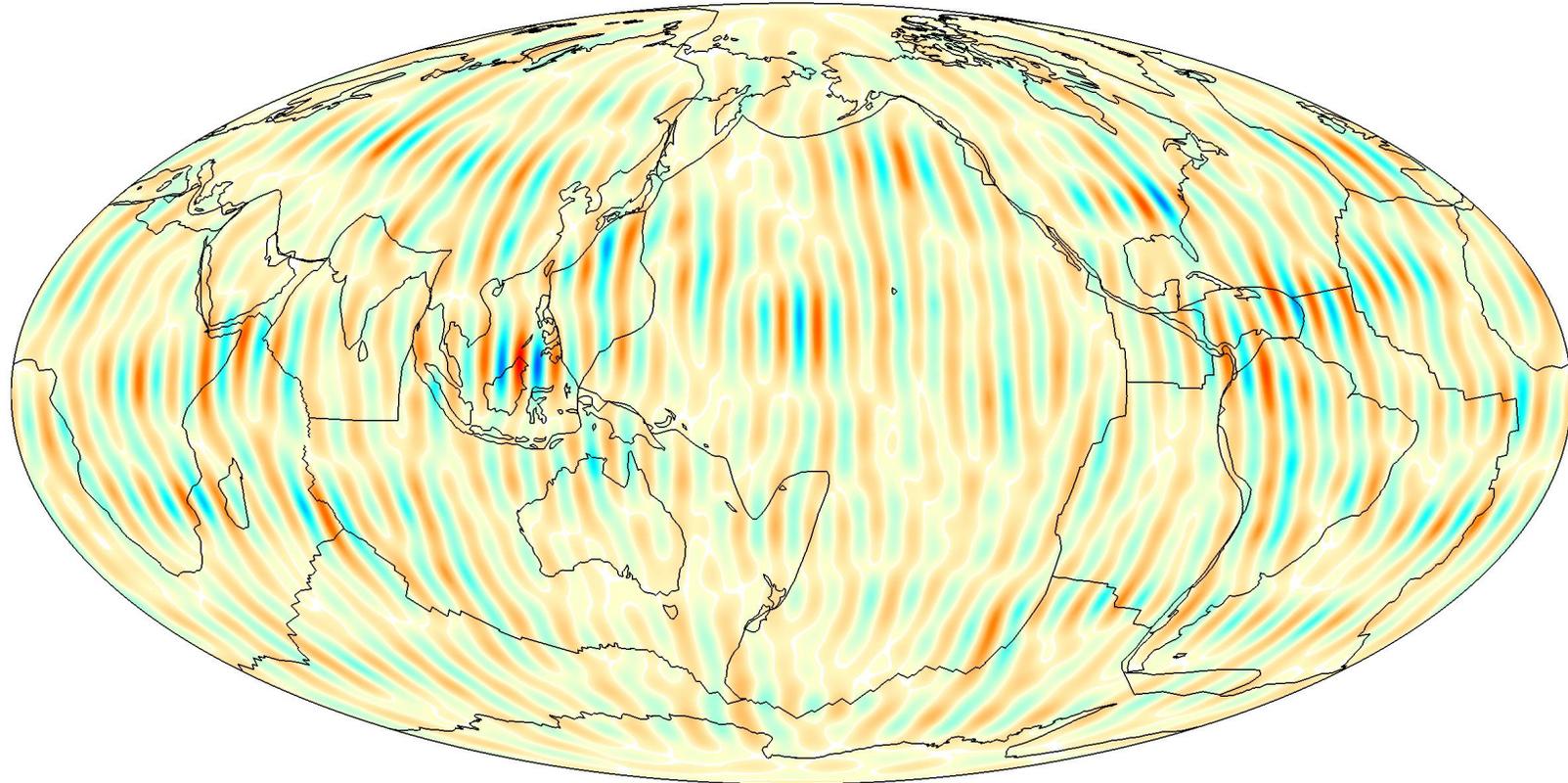
free-air anomaly to $L = 60$ predicted due to M122604A [m/s^2]



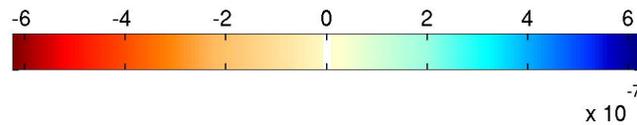


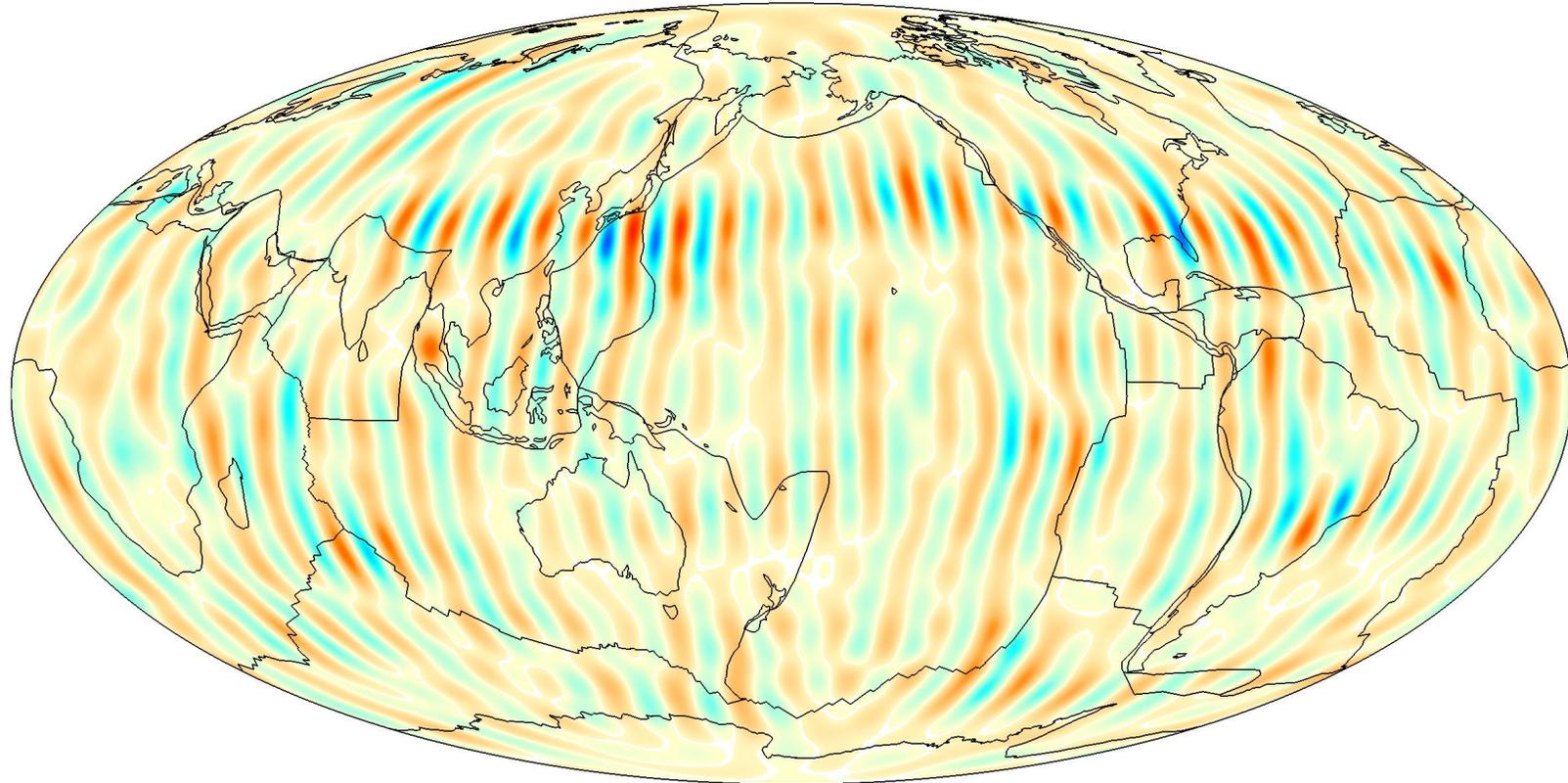
difference in free-air anomaly filtered to $L = 58$ [m/s^2]
between January 2005 and December 2004



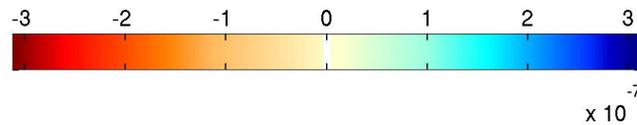


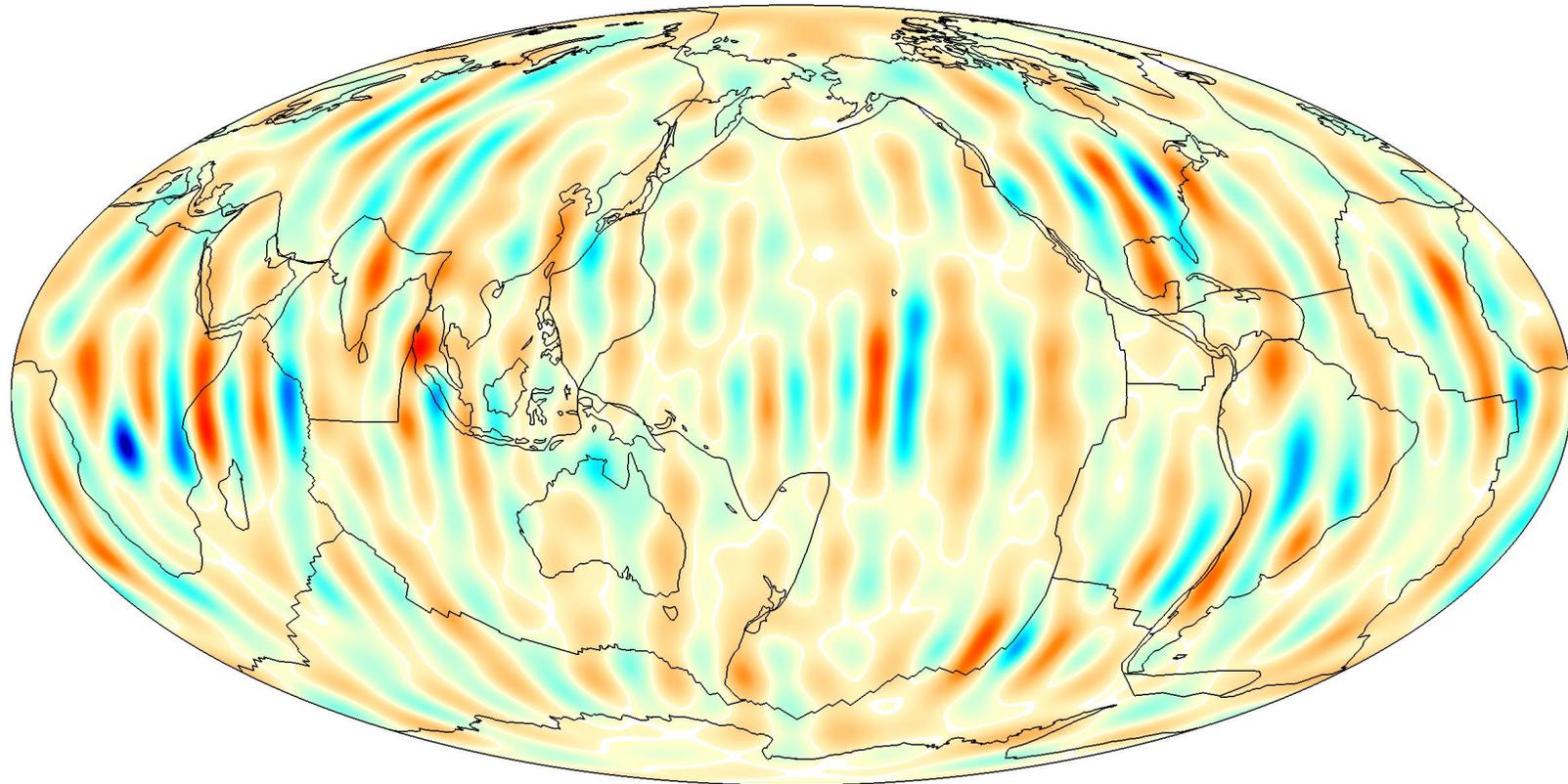
difference in free-air anomaly filtered to $L = 50$ [m/s^2]
between December 2004 and January 2005



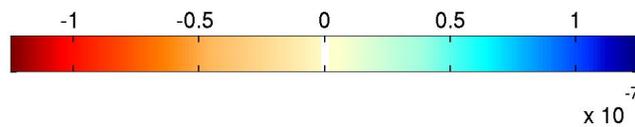


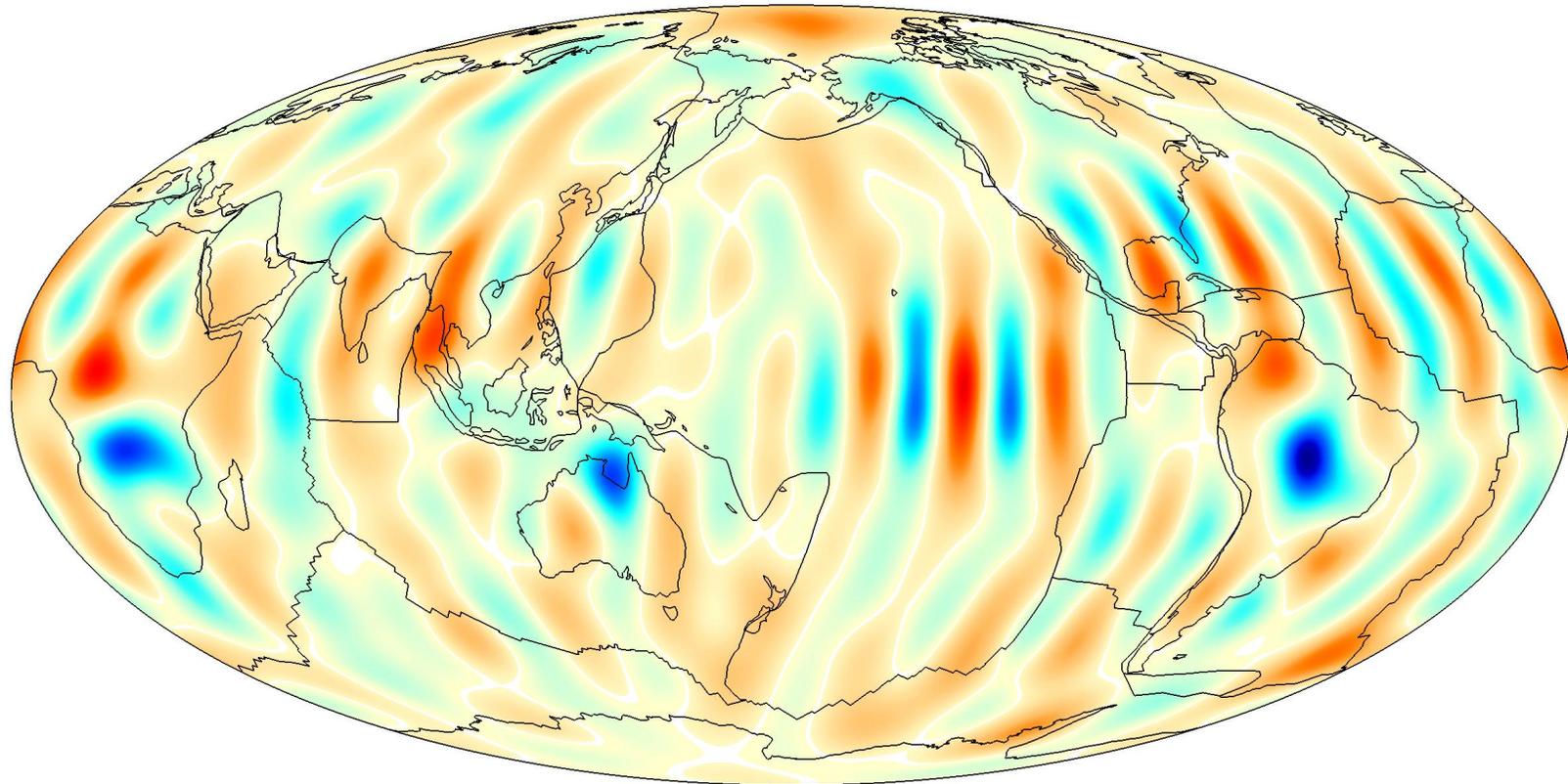
difference in free-air anomaly filtered to $L = 40$ [m/s^2]
between January 2005 and December 2004



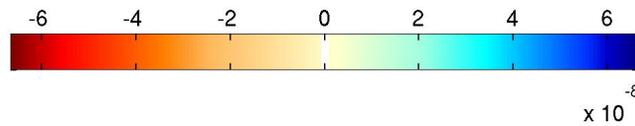


difference in free-air anomaly filtered to $L = 30$ [m/s^2]
between January 2005 and December 2004





difference in free-air anomaly filtered to $L = 20$ [m/s^2]
between January 2005 and December 2004



What GRACE sees and doesn't see

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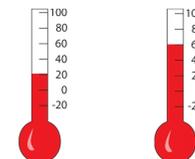
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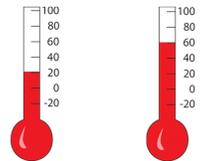
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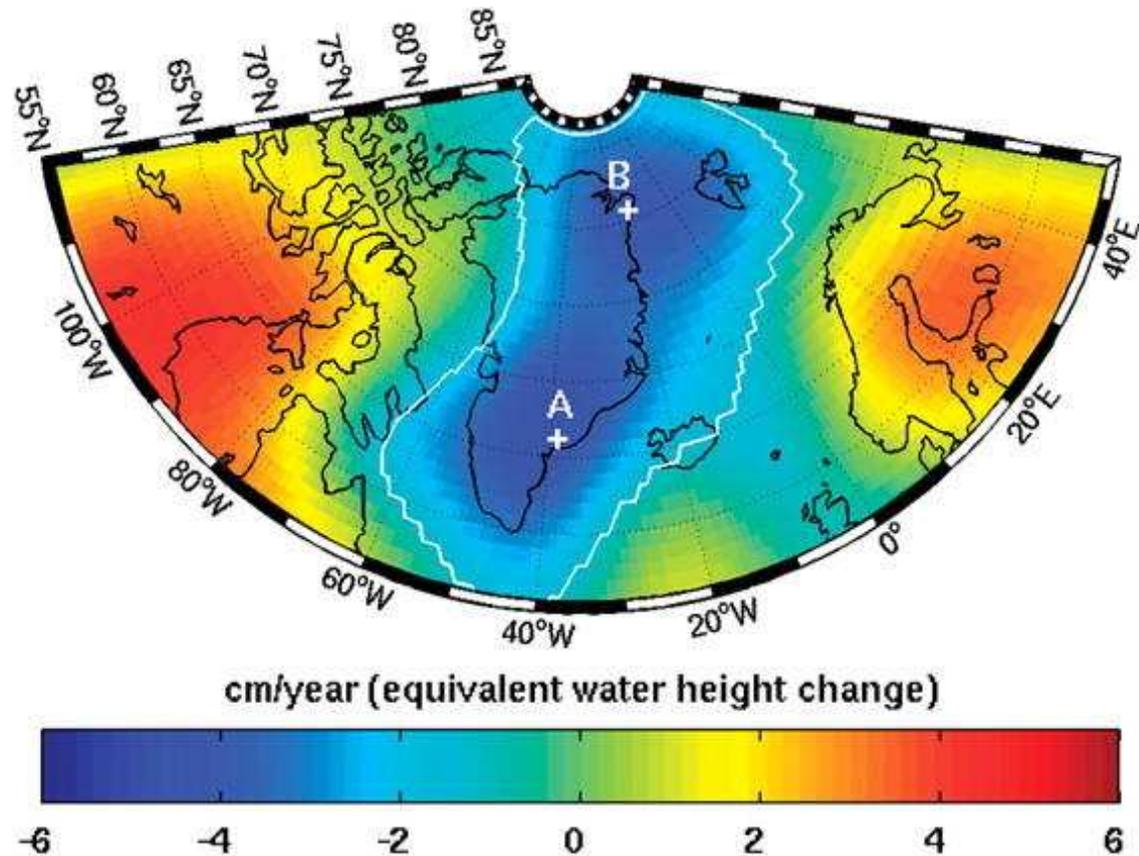
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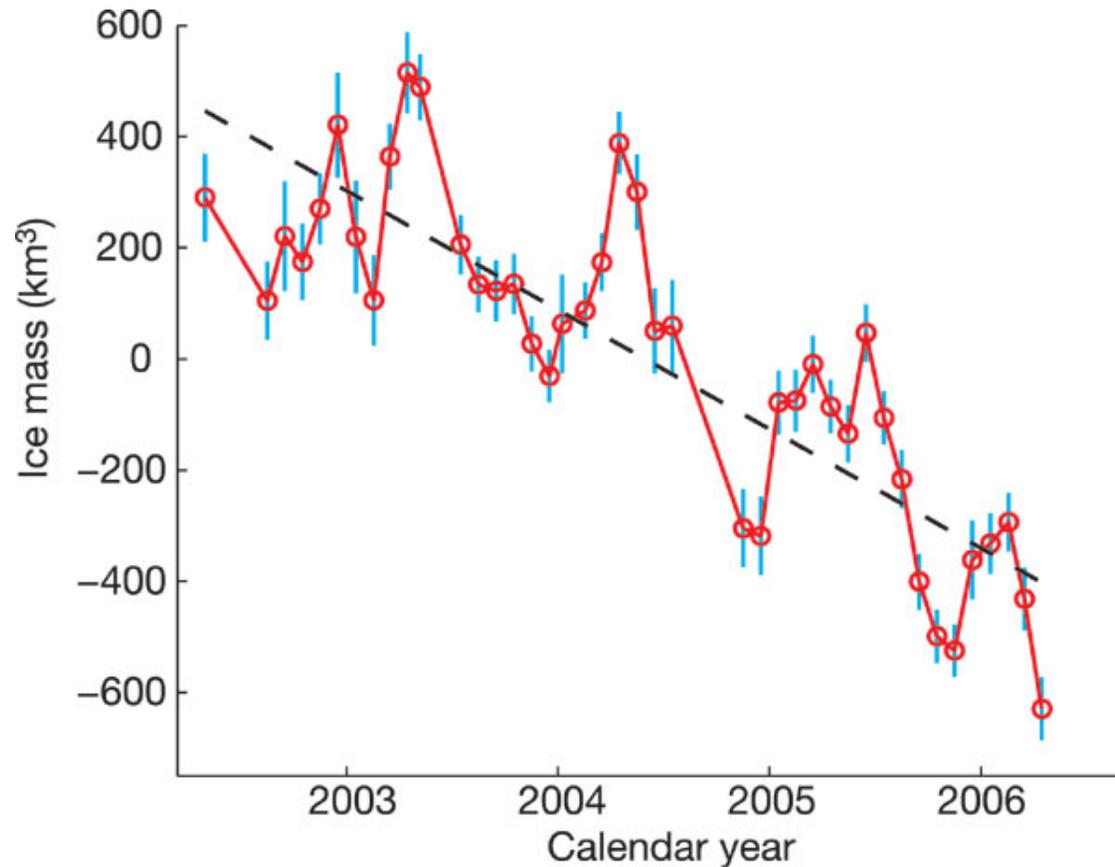
How well does GRACE detect what may be going on with the world's ice caps?

Aware of the huge challenges to beat elevated noise levels at small spatial footprints, the community has developed a multitude of **filtering** methods to **enhance signal-to-noise ratios** and, in particular, to eliminate the prominent effect of the satellite orbits on the behavior of the solutions (**destriping**).



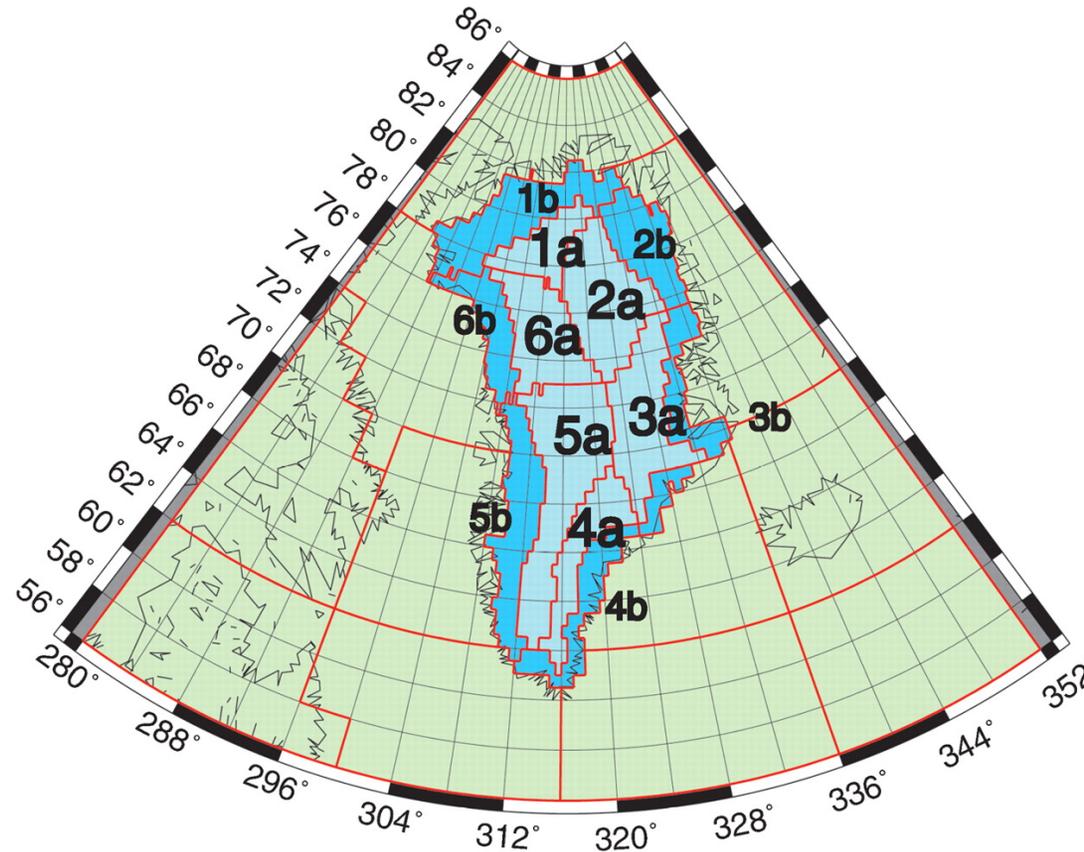
Chen, Wilson & Tapley, *Science* (2006):

“Spatial leakage effects are also evident, because of filtering applied to suppress the noise in high-degree and high-order spherical harmonics.”



Velicogna & Wahr, *Nature* (2006):

“Interpreting the trend as due entirely to a change in ice, and subtracting the leakage trend, we inferred an ice volume decrease of $240 \pm 12 \text{ km}^3 \text{ yr}^{-1}$.”



Luthcke *et al.*, *Science* (2006):

“Our overall Greenland mass trend of $101 \pm 16 \text{ km}^3 \text{ yr}^{-1}$ is a factor of 2 smaller than the recent GRACE-based trend determined by Velicogna & Wahr (2006).”

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 - Authors *disagree* on matters as fundamental as the **choice of basis** to represent the solution. Pixels? Mascons? Spherical harmonics?
How do these choices influence the results?
-

The data **collected in** or **limited to** R are **signal plus noise**:

We may assume that $n(\mathbf{r})$ is **zero-mean** and **uncorrelated** with the signal,

and consider the **noise covariance**:

In other words: we've got **noisy** and **incomplete** data, on a sphere, Ω .

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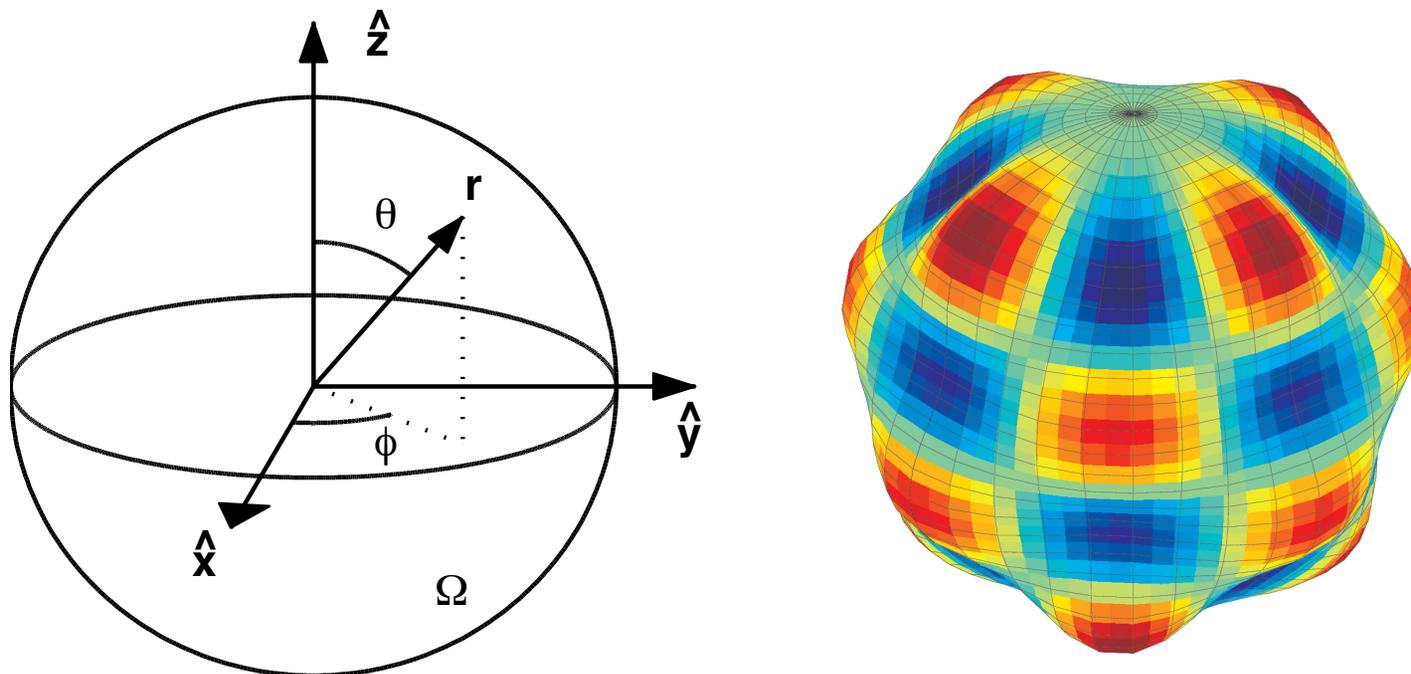
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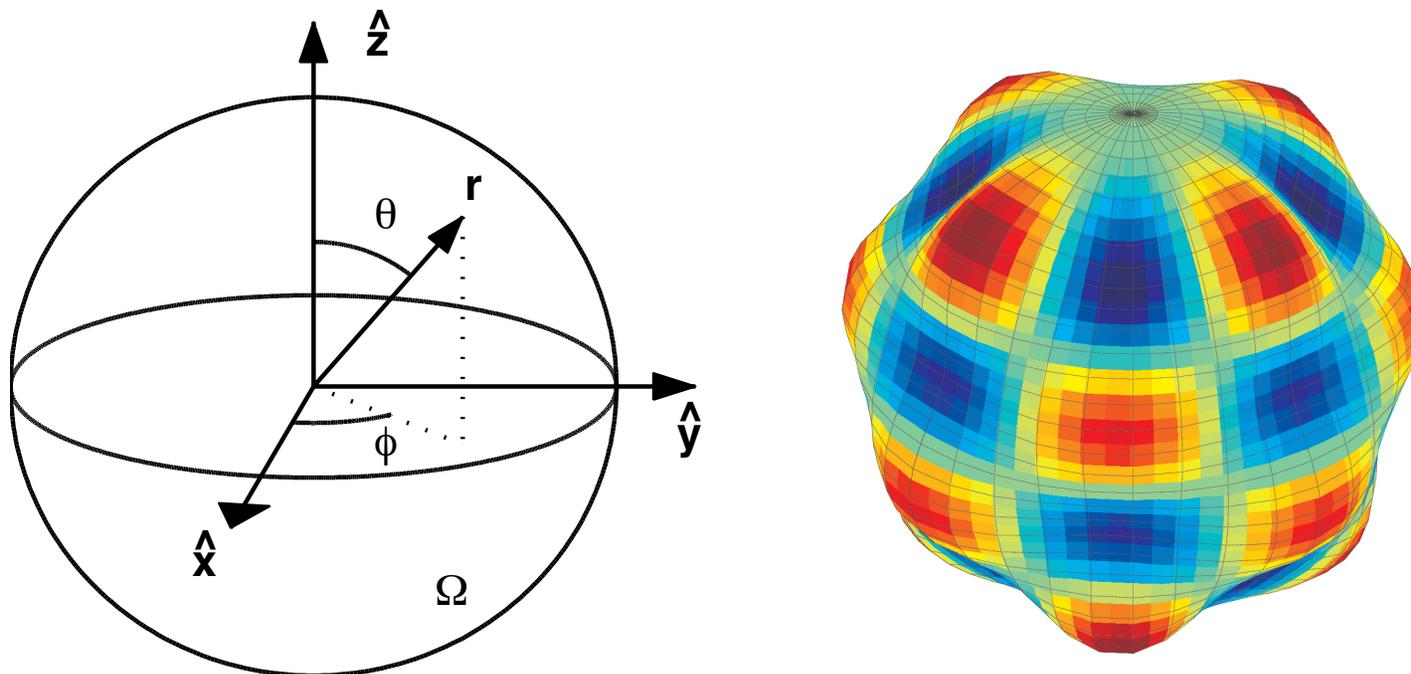
To honor the spherical shape of the Earth,
we work in the **spherical-harmonic** basis.

Scalar signals $s(\mathbf{r})$ modeled on a unit sphere Ω :



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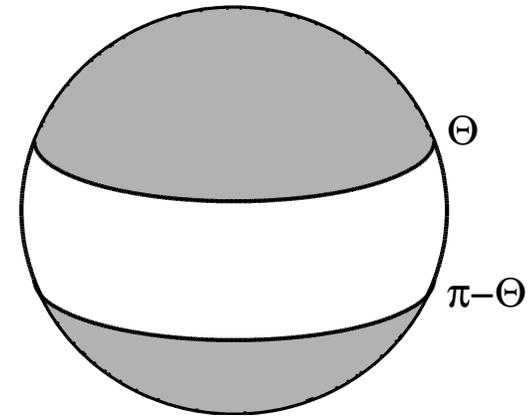
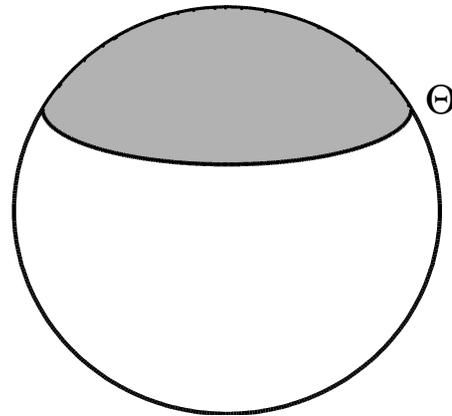
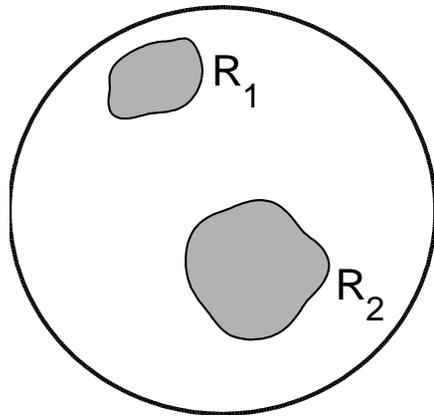
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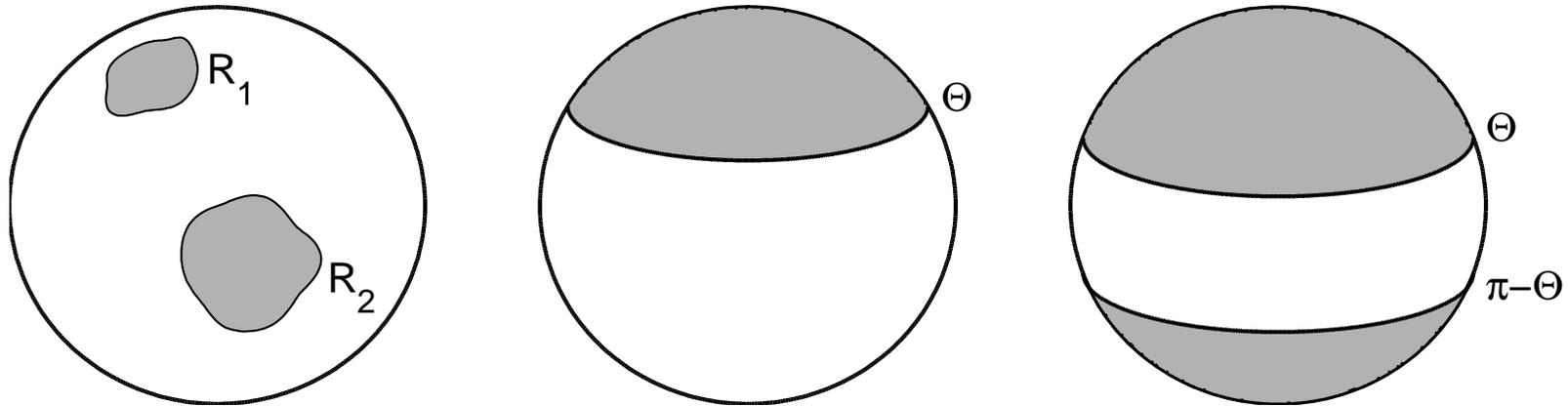
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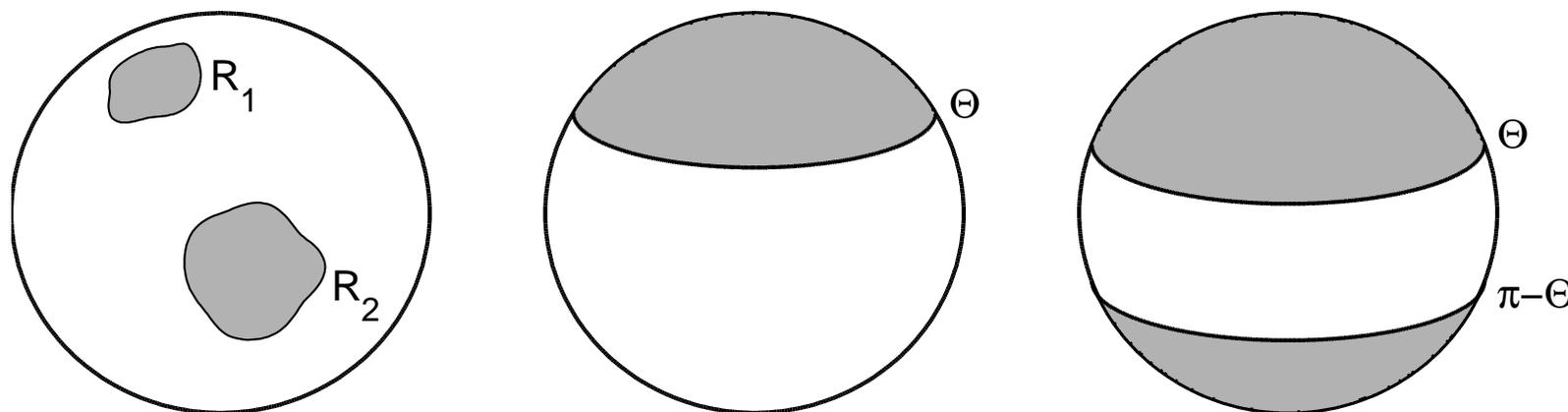
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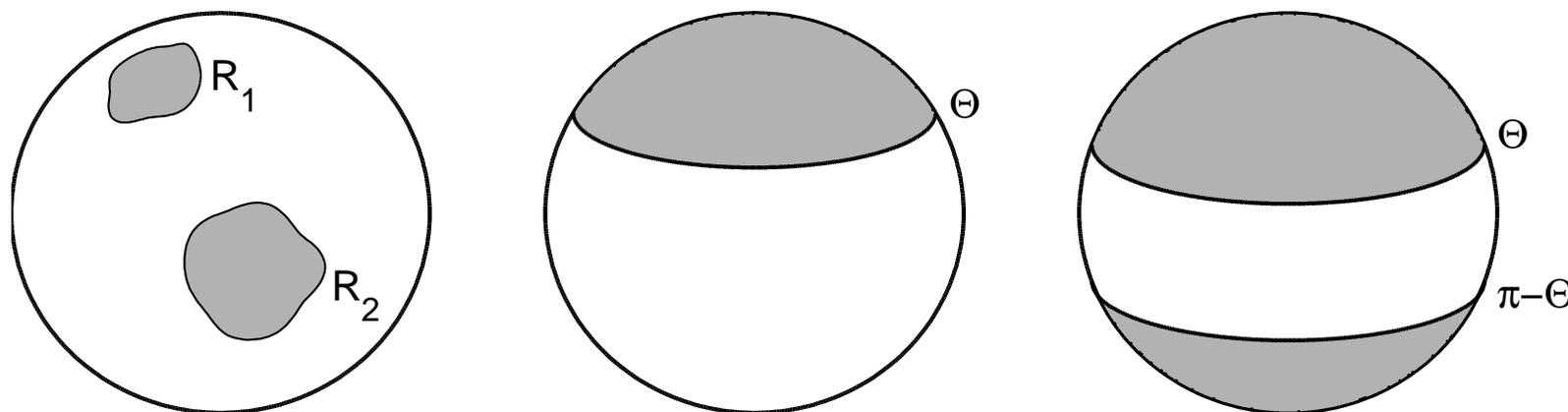
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These new, **doubly orthogonal**, functions are called **Slepian functions**, $g(\mathbf{r})$.

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that satisfy **Slepian's concentration problem** to the region R of area A :

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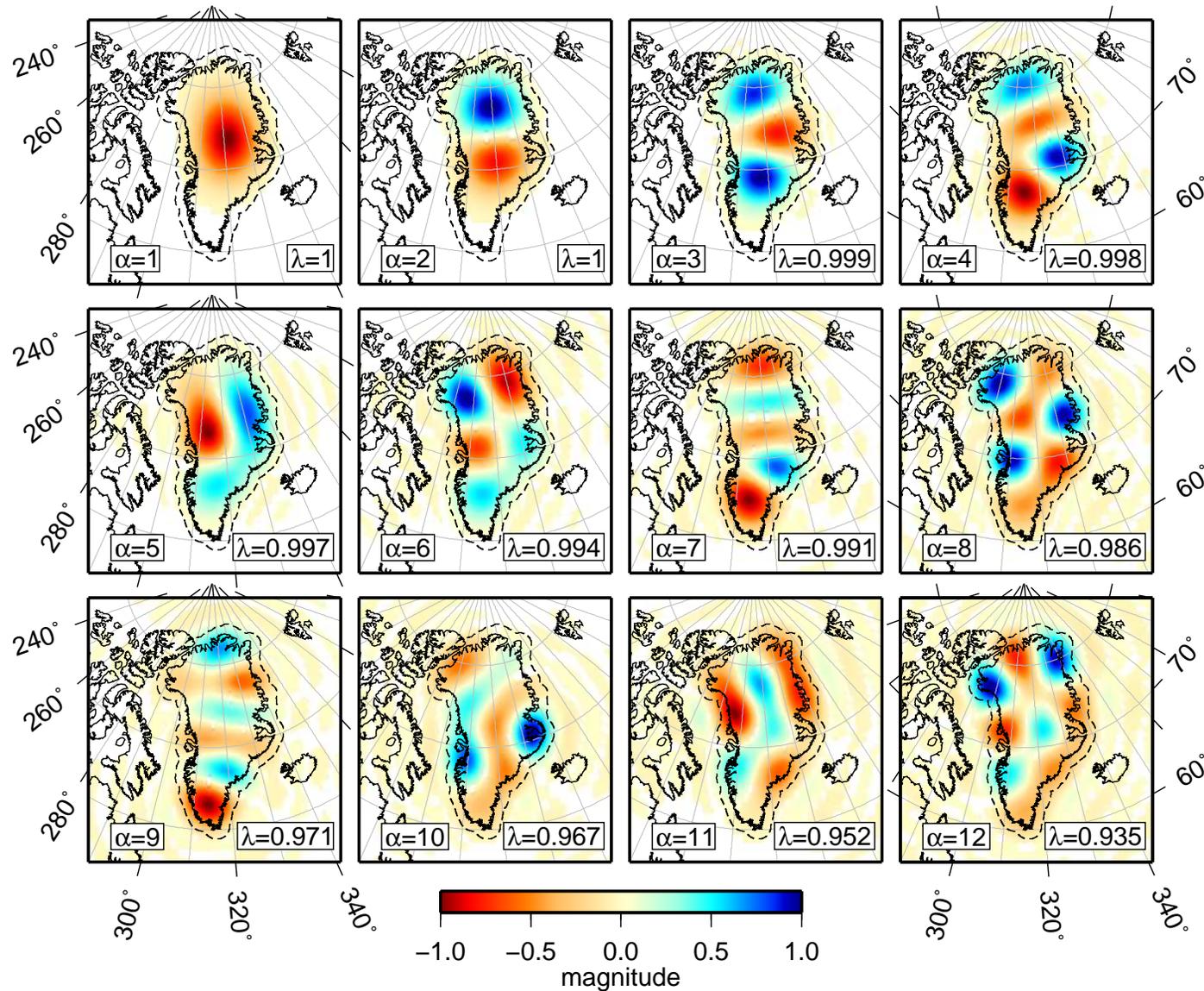
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Voilà! We have concentrated a poorly localized basis of $(L + 1)^2$ functions, Y_{lm} , both spatially and spectrally, to a new basis with only about K functions, g .

Slepian functions for Greenland, $L = 60$



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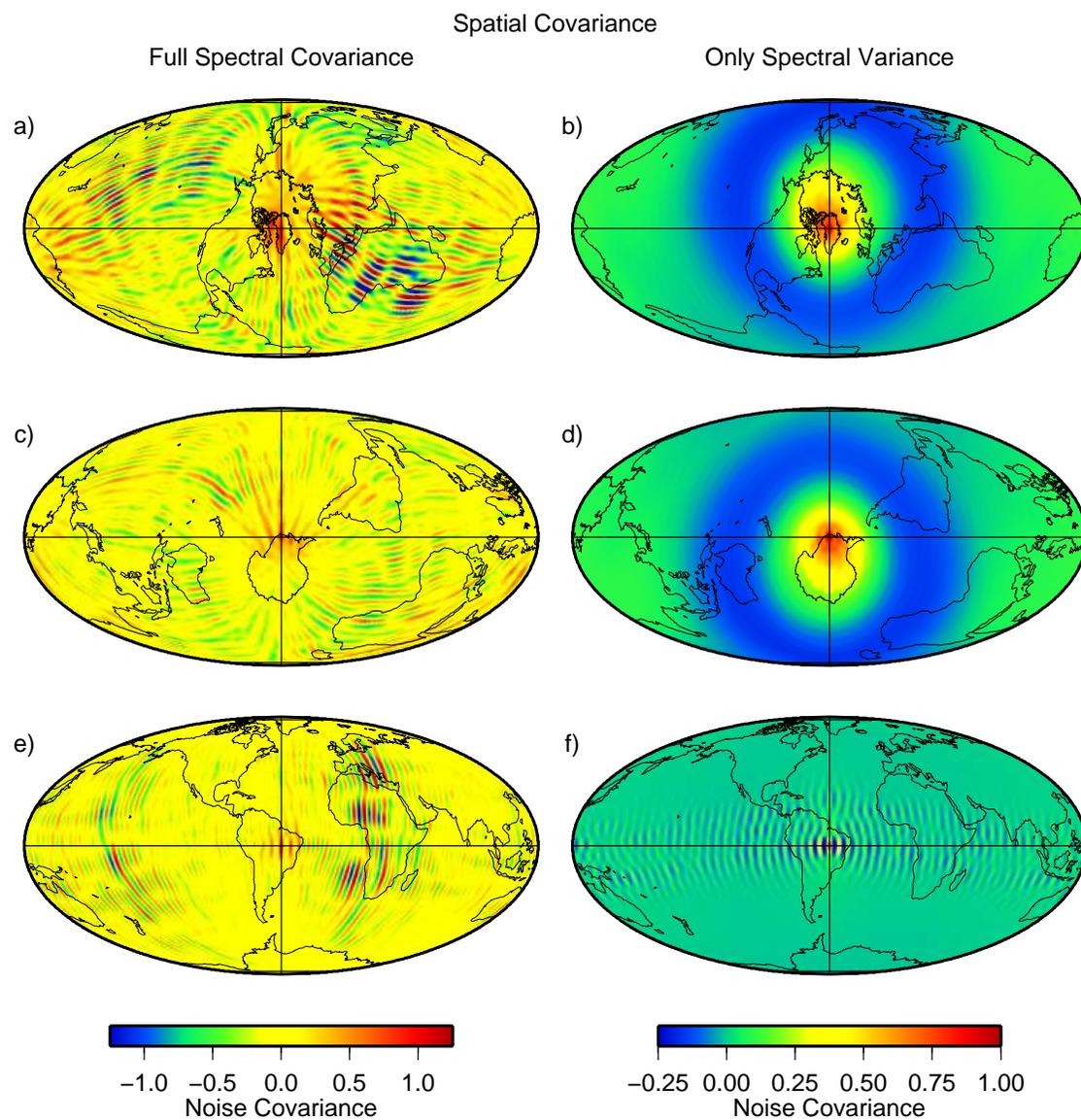
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4. In this philosophy, the signal is **projected** onto the basis in which signal-to-noise ratios are maximized, and all subsequent estimates take the full spatial and spectral noise **covariance** into account.

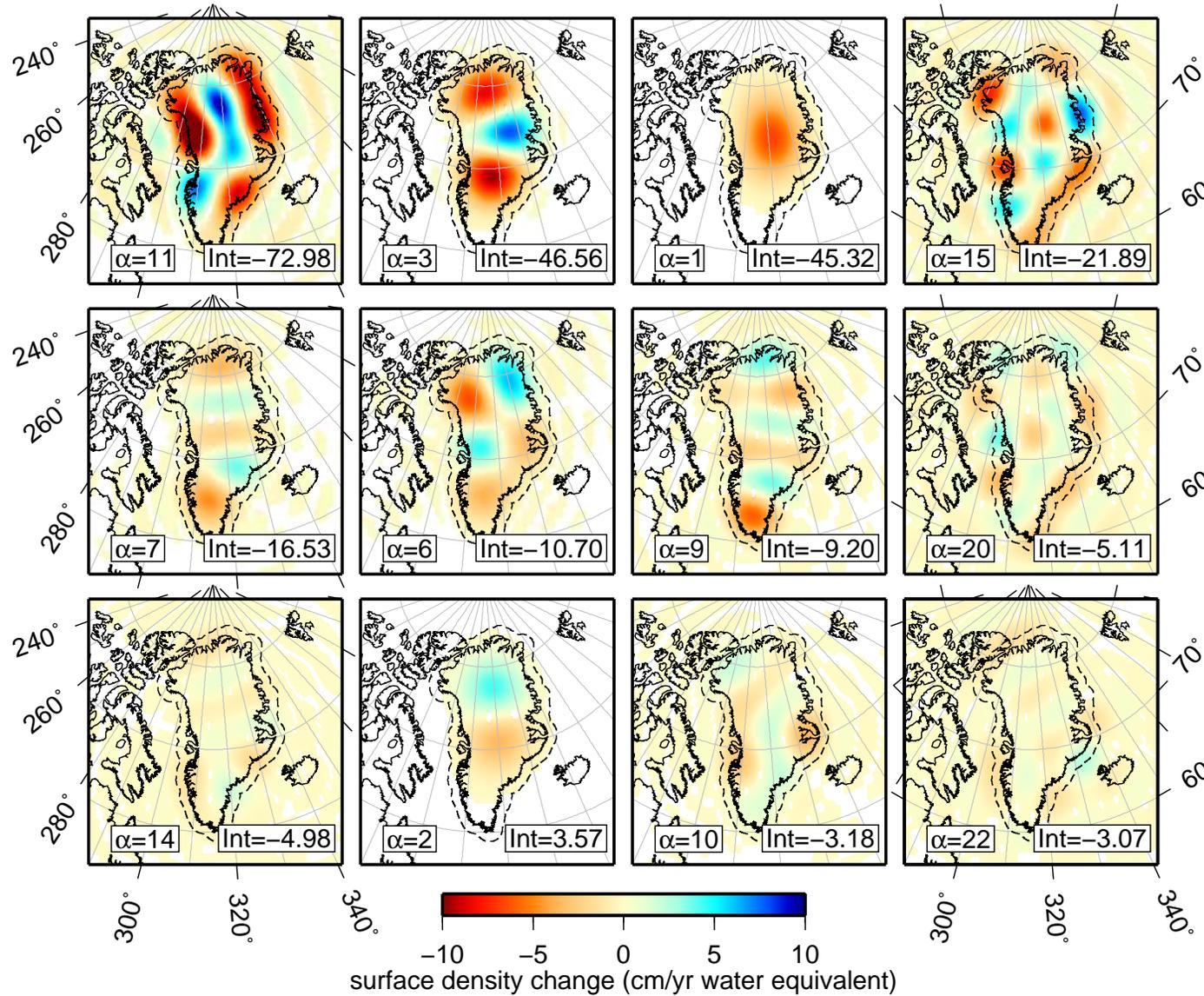
1. Learn as much as possible about the **noise** and the structure of the **signal**.
More than likely, this is an **iterative** procedure.
 2. Design basis functions **appropriate for the region** of interest.
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 5. This is *very* different from most other approaches, though in spirit, it is *identical* to the stuff Slepian, Shannon and Wiener figured out in the 1950s.
-

I. Look at the noise (in the pixel basis)

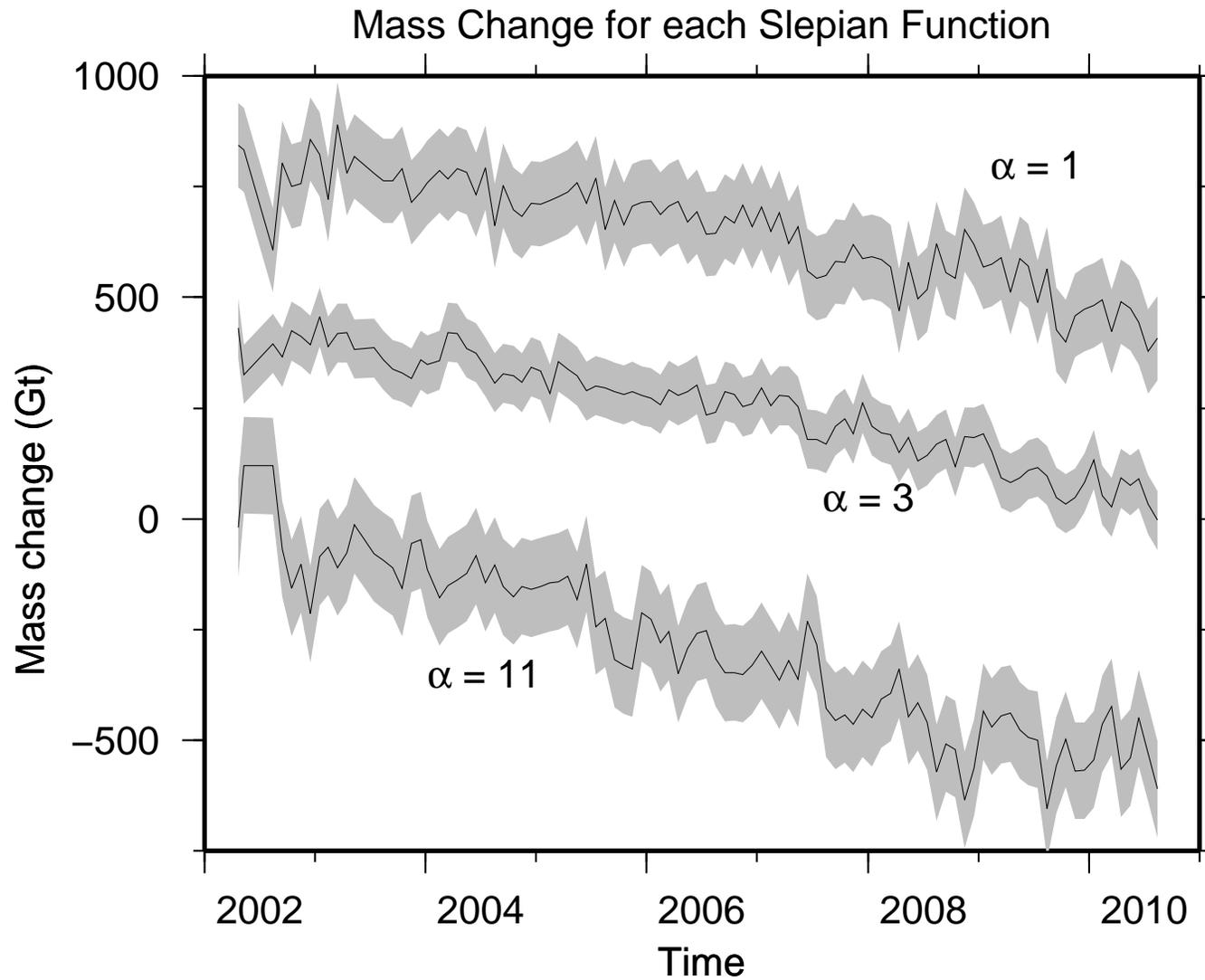
30/57



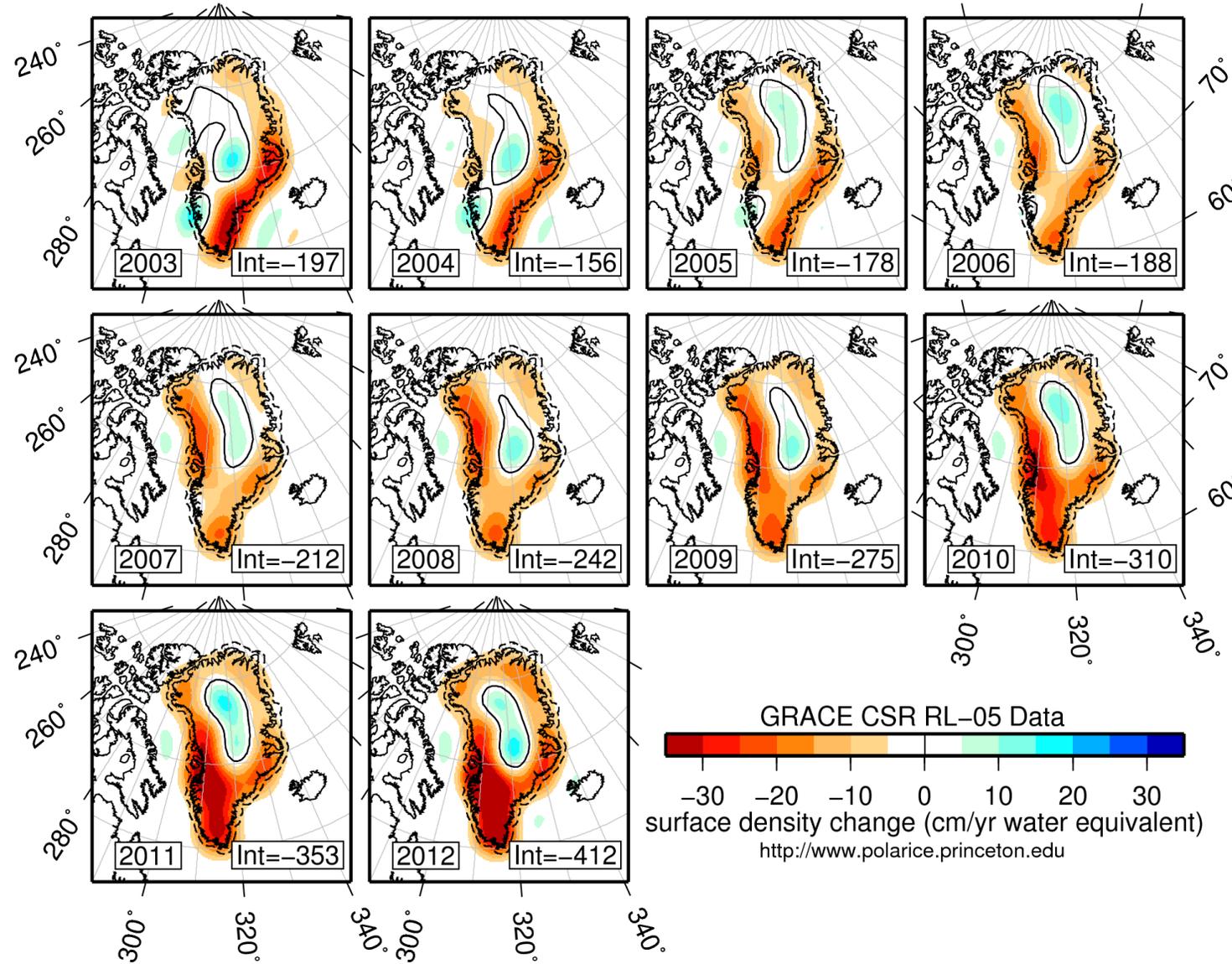
II. Project the signal onto the Slepian basis



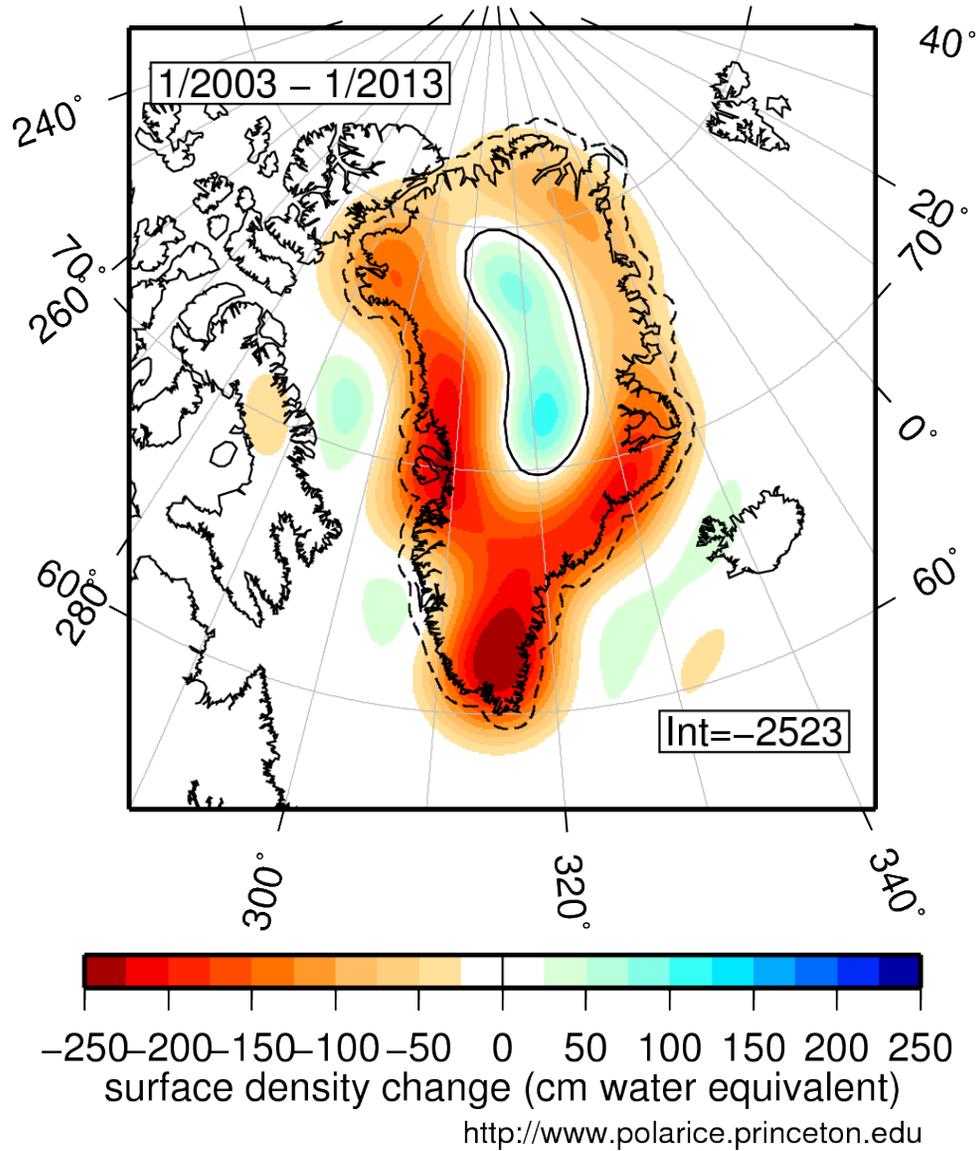
III. Solve for the time-dependence



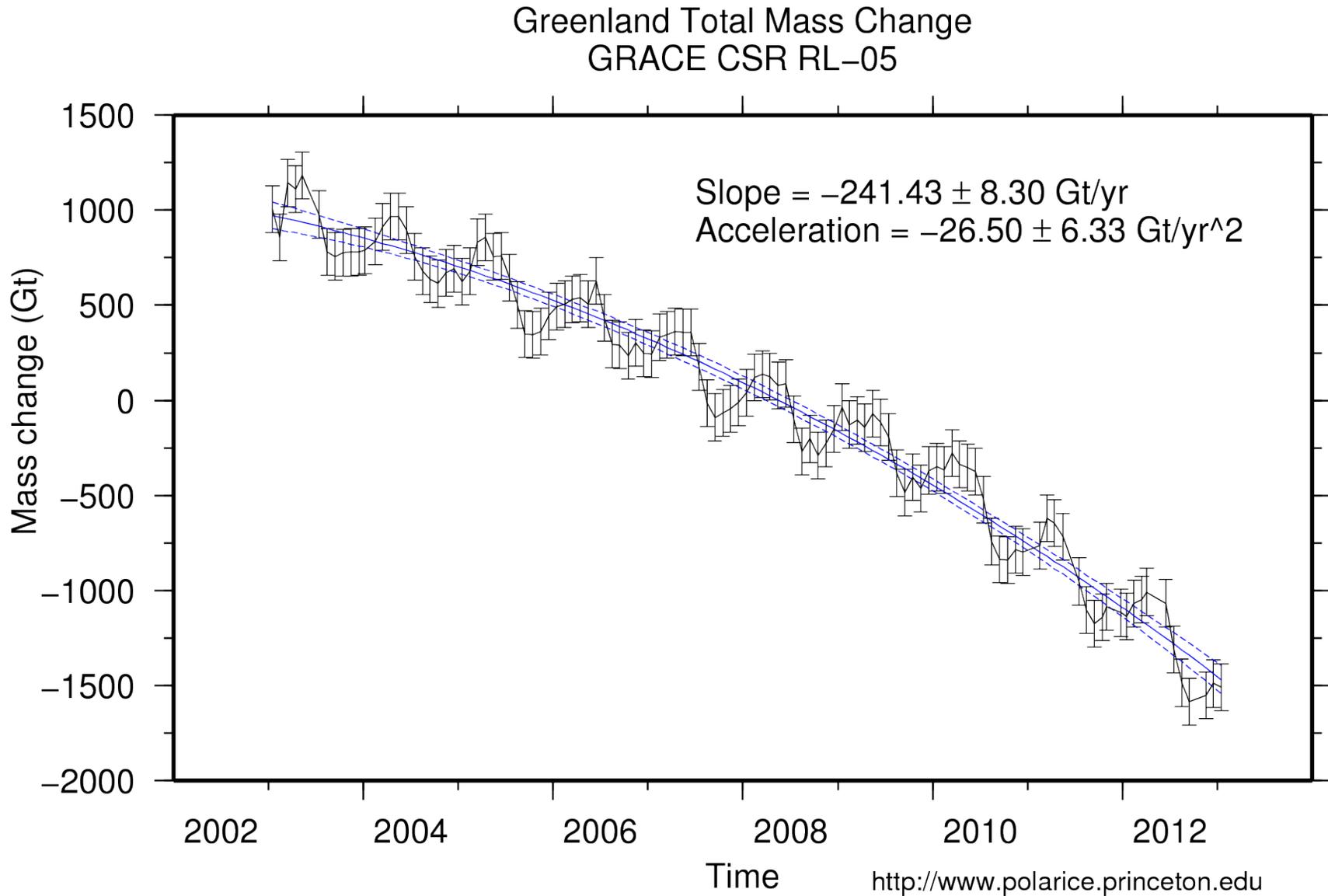
IV. Temporal variations of the spatial pattern



V. Spatial pattern 2003–2013



V. Invert for the total budget (if you must)



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 - Maps of the time-averaged mass loss show a marked concentration at the **outlet glaciers**. Observed rates compare well with GPS surveys.
-

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 - On balance, the Greenland ice loss accounts for only a **minor fraction** of the Earth's sea level rise rate.
 - Let us turn to the geological record to study **sea level change** on a global and regional scale.
-

Data Example I

San Salvador, Bahamas



Reef terrace dominated by *Acropora palmata*

Altitude: 1.5 ± 1.0 m

Age (U/Th): 128.4 ± 8.0 ka

Depositional range: 0-5 m below mean low tide level

Subsidence rate: 1-2 cm/ky



<http://www.mnstate.edu/leonard/G390BPHOTOS.html>

Chen et al.
(1991)

Data Example II

Rio Grande do Sol, Brazil

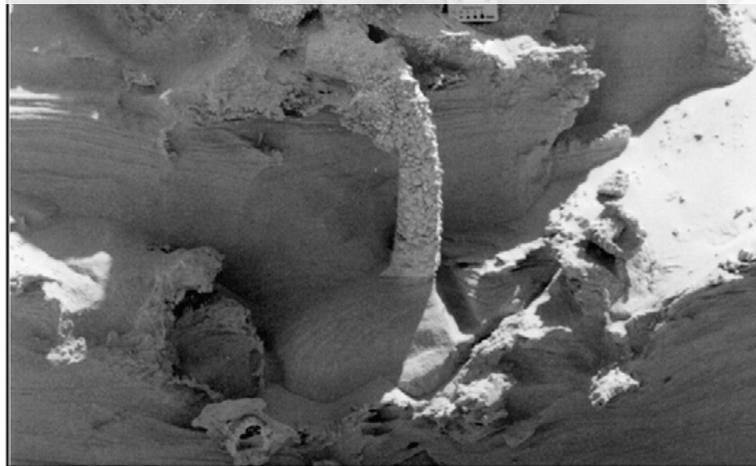


Coastal barrier with *Ophiomorpha* burrows

Altitude: 6.4 ± 1.5 m

Age (TL): 125 ± 17 ka (generic LIG)

Depositional range: low-tide



Data Example III

Portland East, England



Raised beach

Altitude: 11 ± 1 m

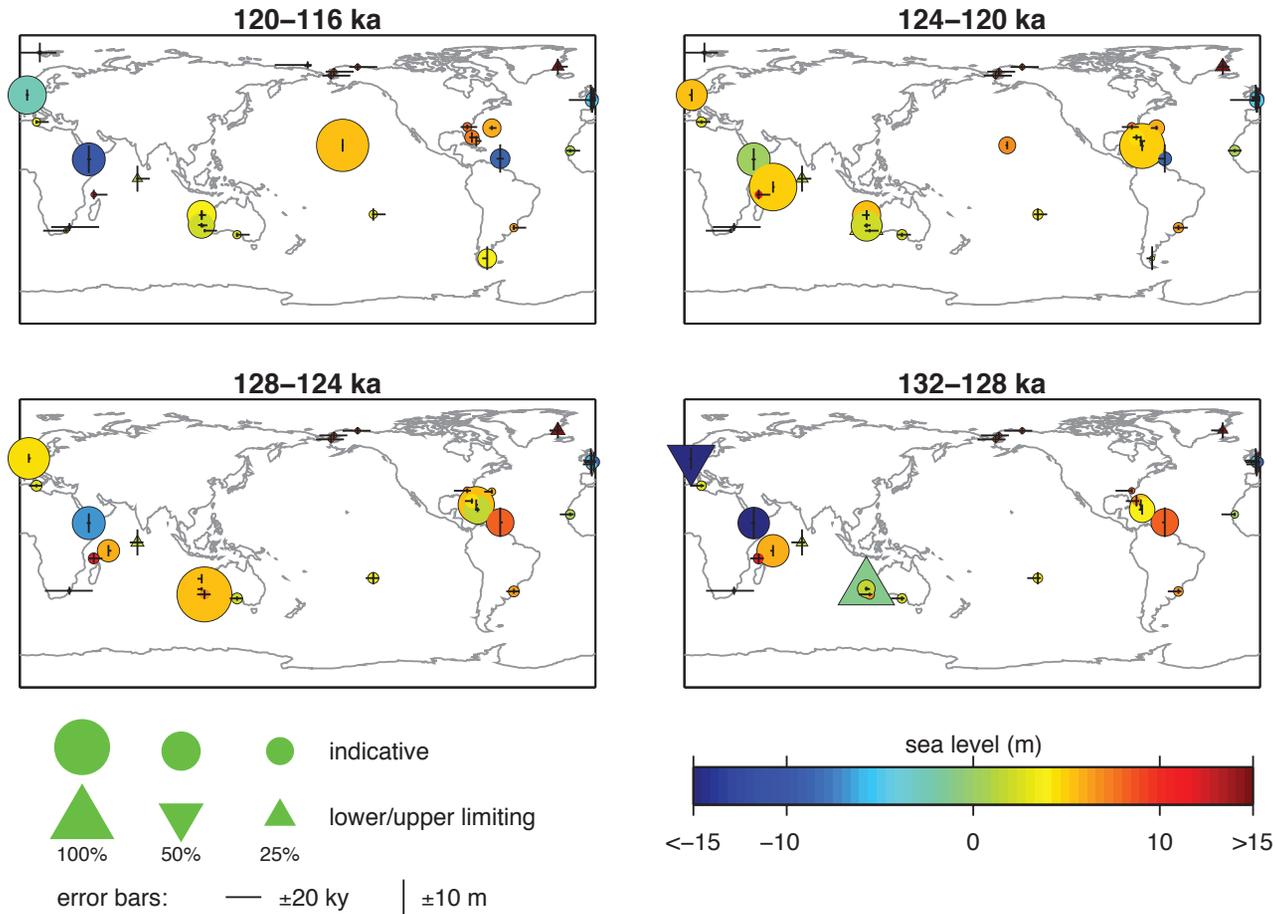
Age: 125 ± 17 ka (generic LIG)

Depositional range: between mean low and high tides

Uplift rate: 7-14 cm/ky (!)



Geological Sea Level Indicators



A very sparse and noisy sample of local sea level indicators

- The data are *very* **noisy** and definitely **incomplete**, both in *spatial* and *temporal* coverage

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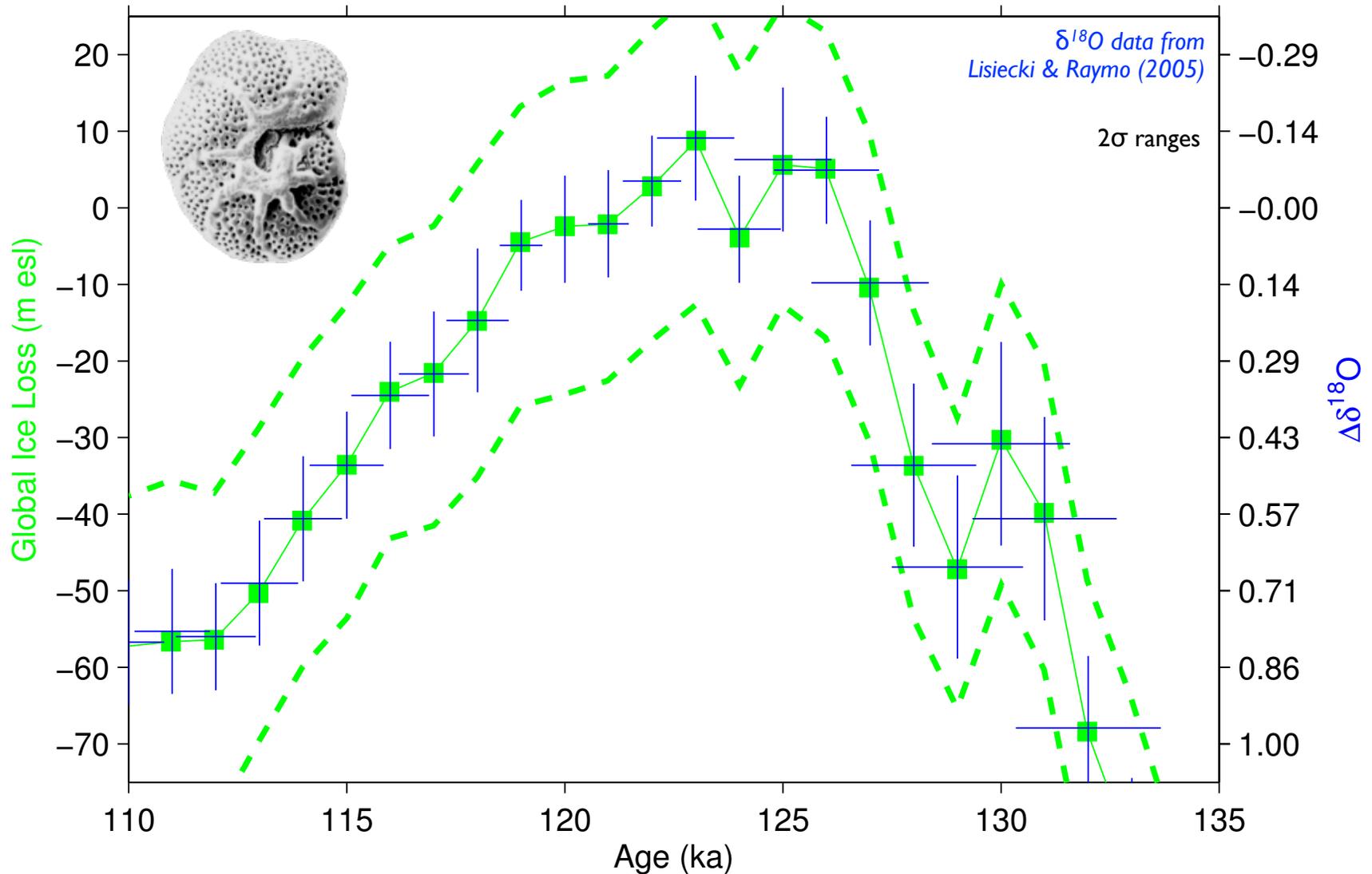
And then we sample thousands and thousands of models to come up with
a **global sea level curve** for the Last InterGlacial

Any **dynamic sea level modelling** must include gravitational, elastic, rotational, isostatic, shoreline migrations, isostasy and tectonics! From our prior solutions and constraints, Jerry Mitrovica built a series of sea level curves for us, which we turned it our posterior:

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$$\underbrace{p(\mathbf{s})}_{\text{prior}} \rightarrow \underbrace{p(\mathbf{d}|\mathbf{s})}_{\text{"model"}} \rightarrow \underbrace{p(\mathbf{s}|\mathbf{d})}_{\text{posterior}}$$

Oxygen isotopic record of global ice volume



Cartoon from: http://earthguide.ucsd.edu/virtualmuseum/climatechange2/01_1.shtml

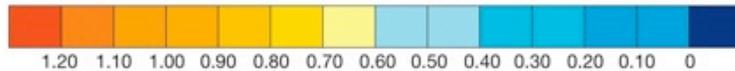
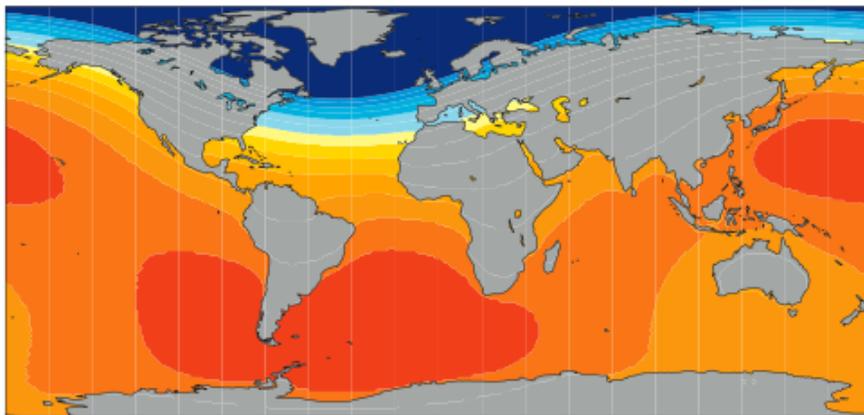
Our Sea Level Model

Effects included:

Gravitational, elastic, rotational, isostatic, shoreline migrations

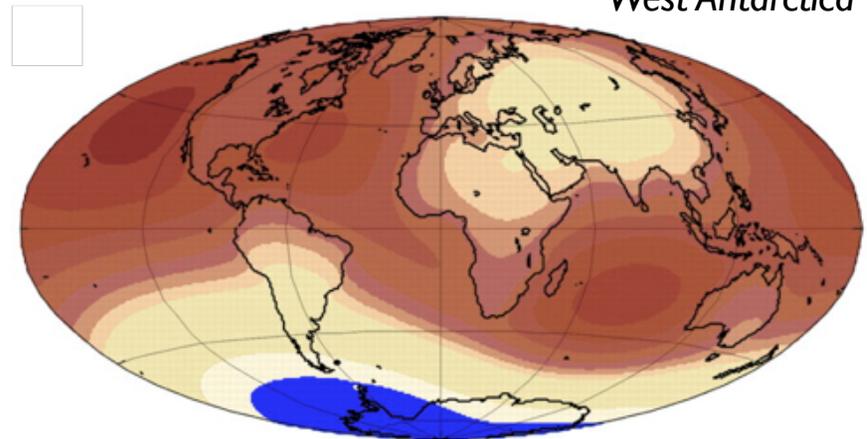
Example: “*Fingerprints*” of Greenland and West Antarctic Ice Sheet melting, per meter global sea level rise

Greenland

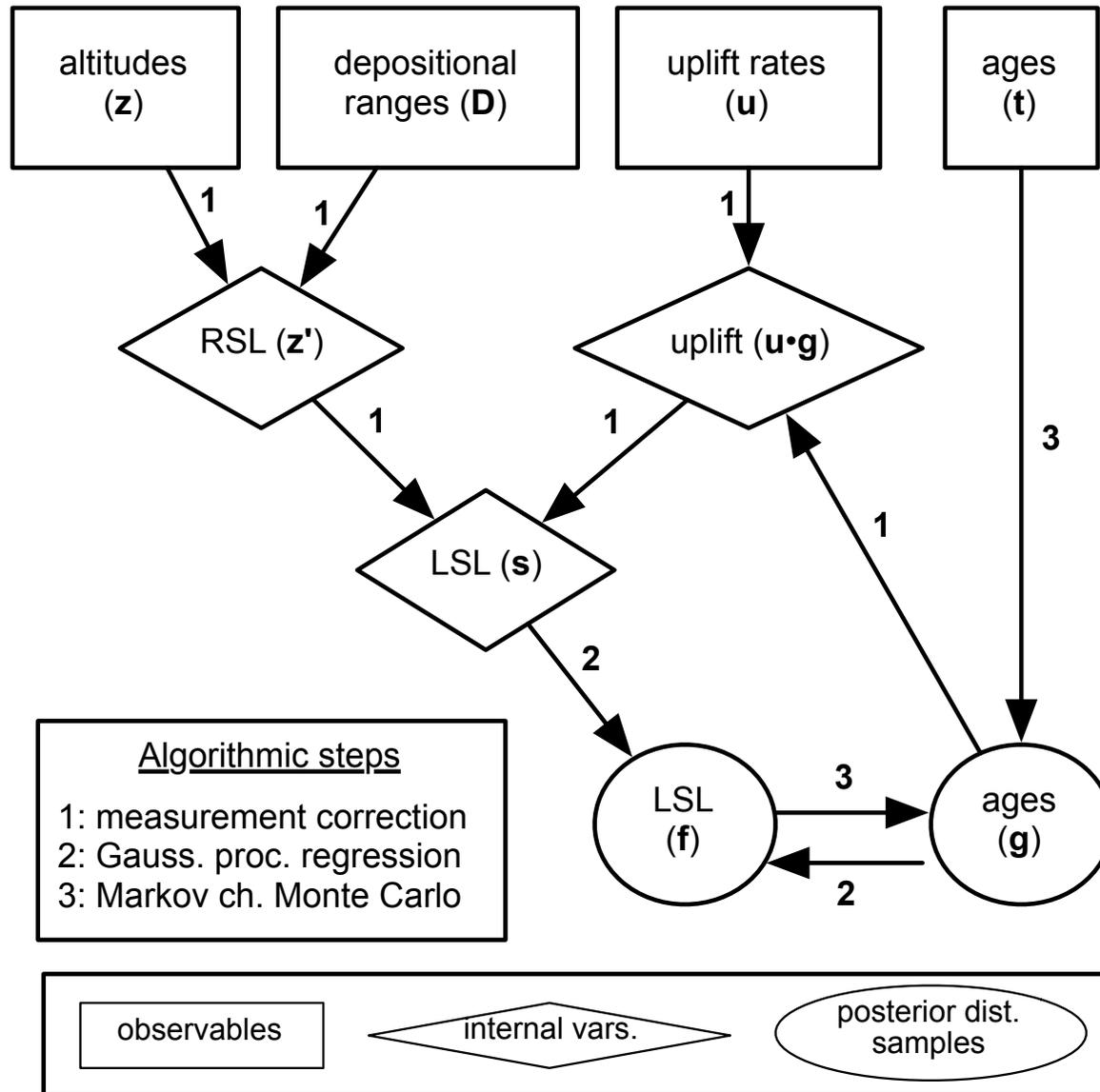


Mitrovica et al. (2001)

West Antarctica

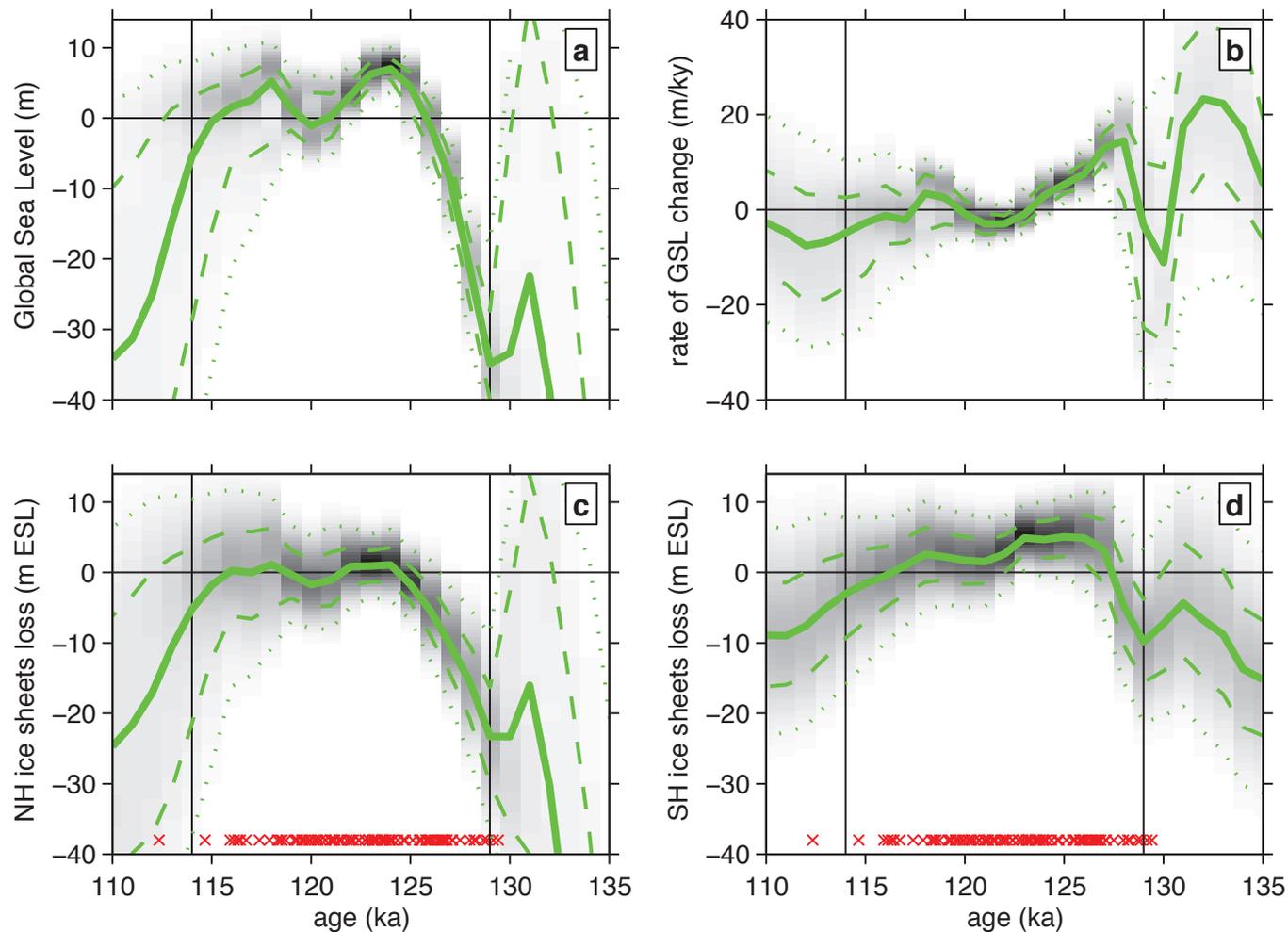


Mitrovica et al. (2009)

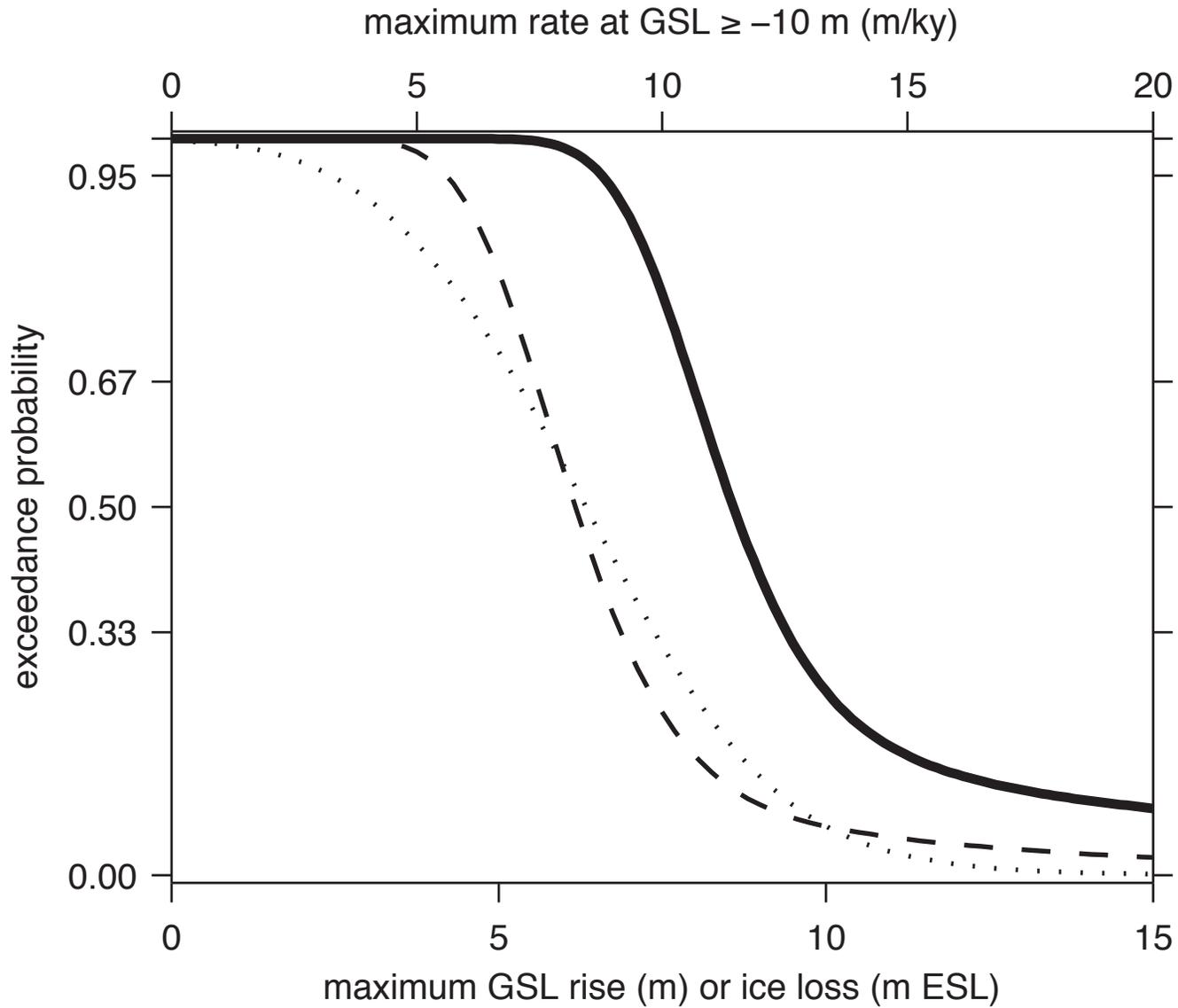


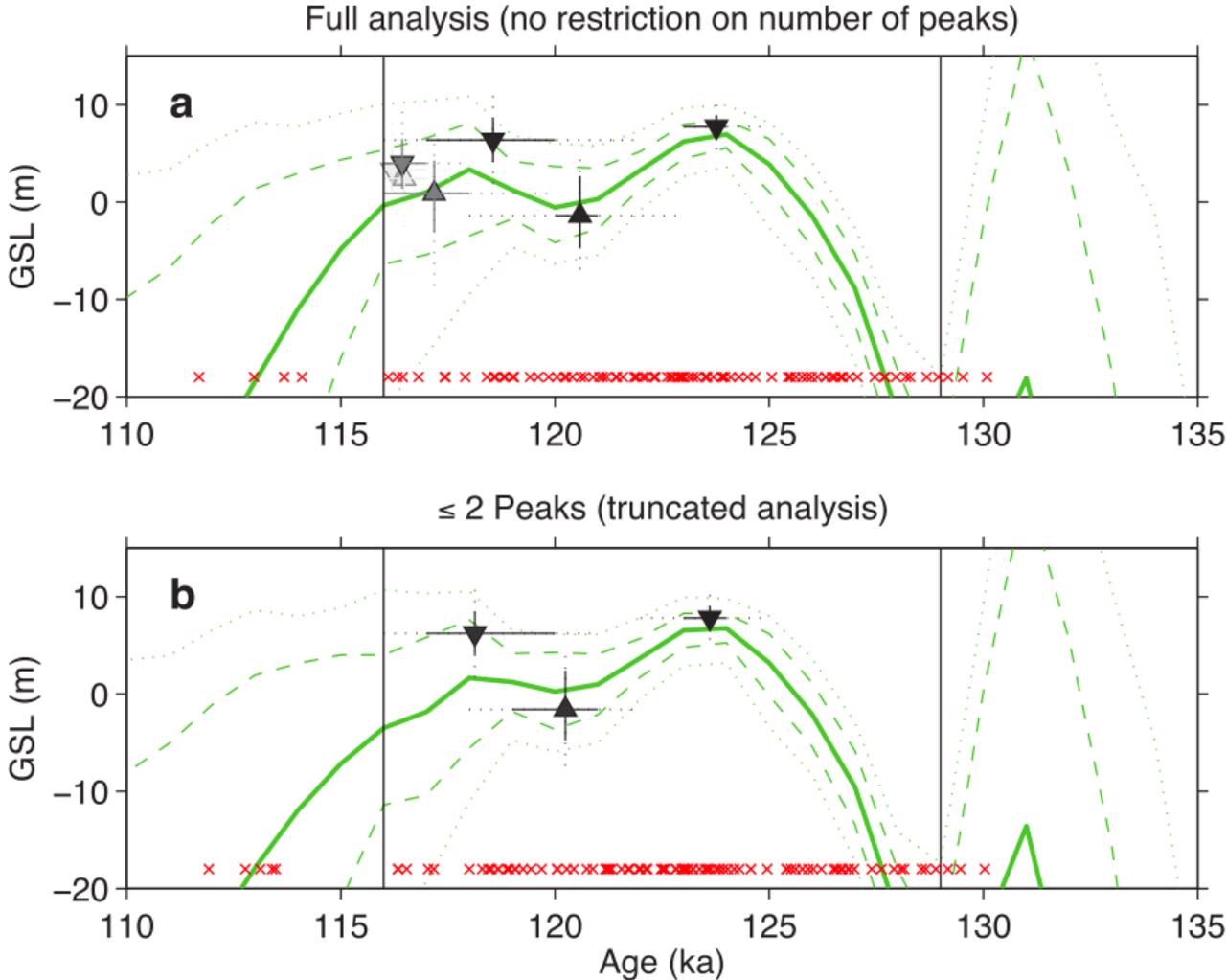
Sea level during the Last InterGlacial...

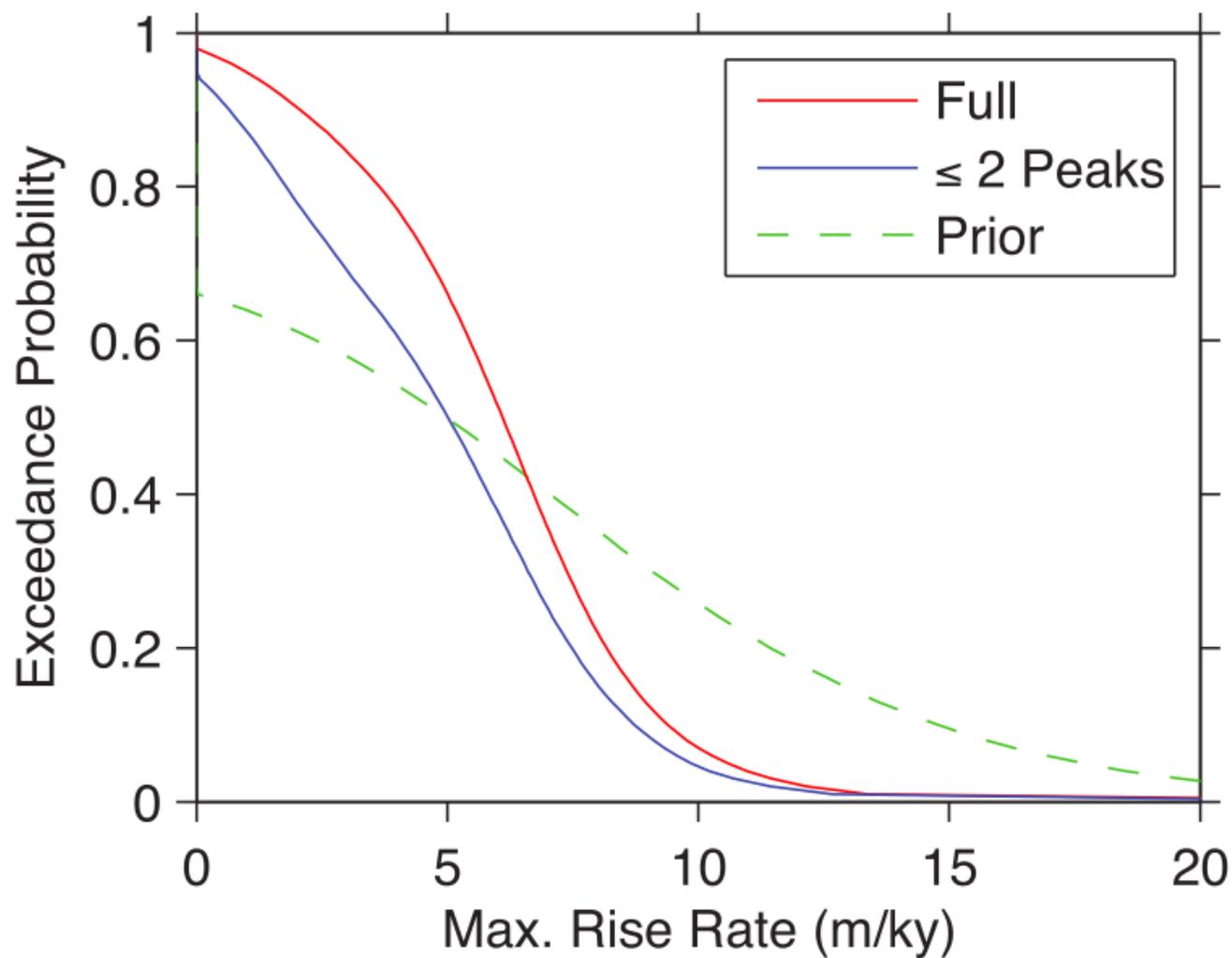
47/57



...a clue to future sea level?



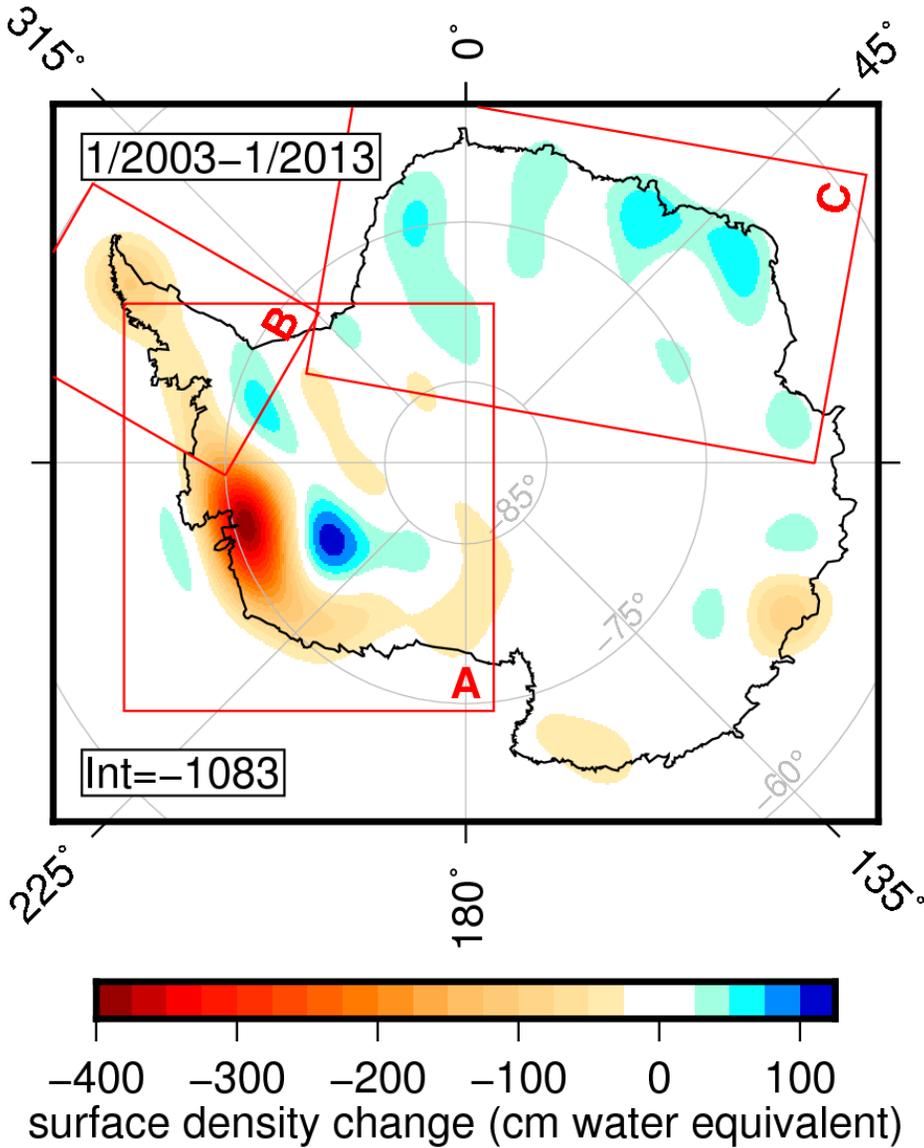


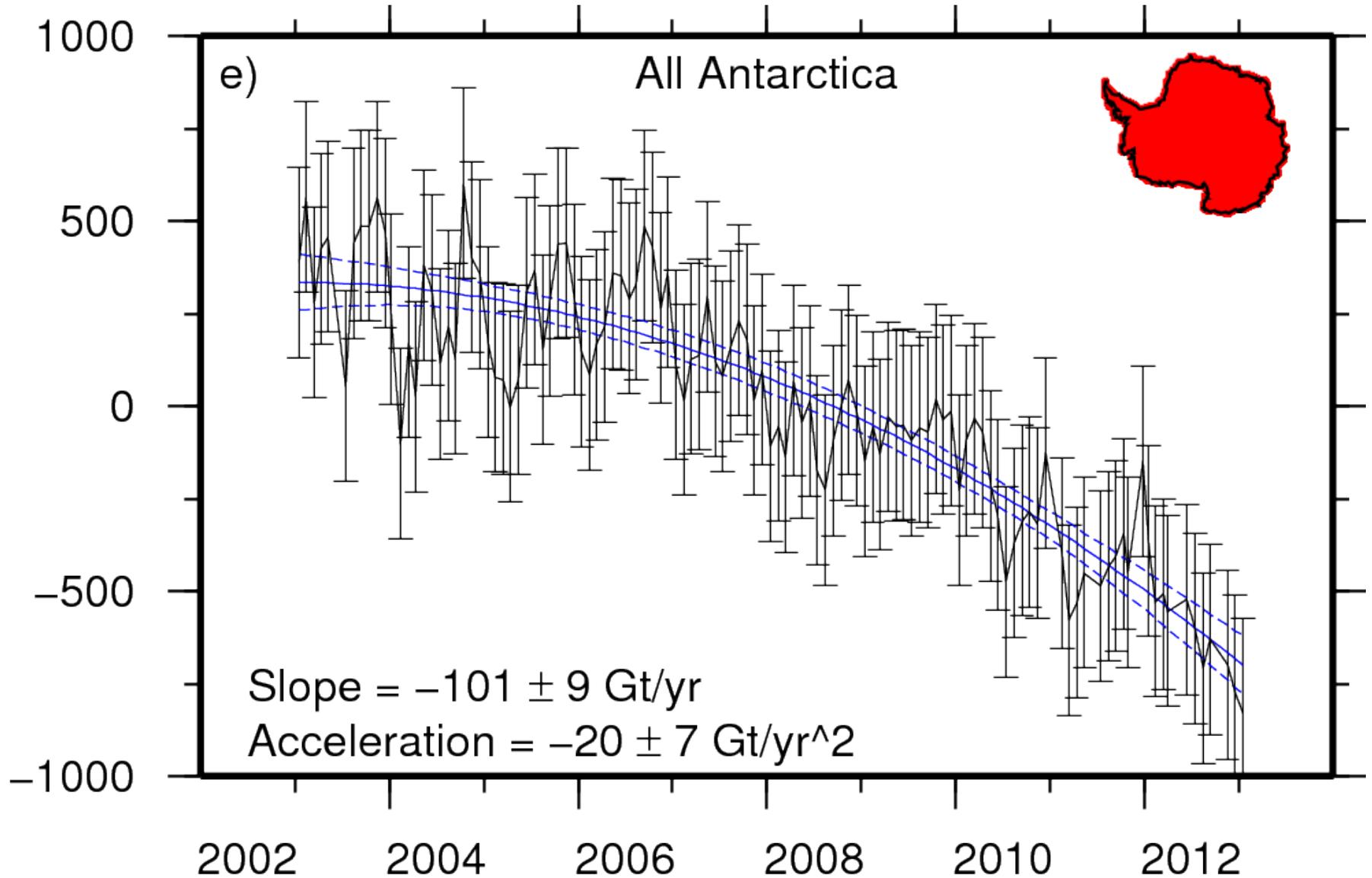


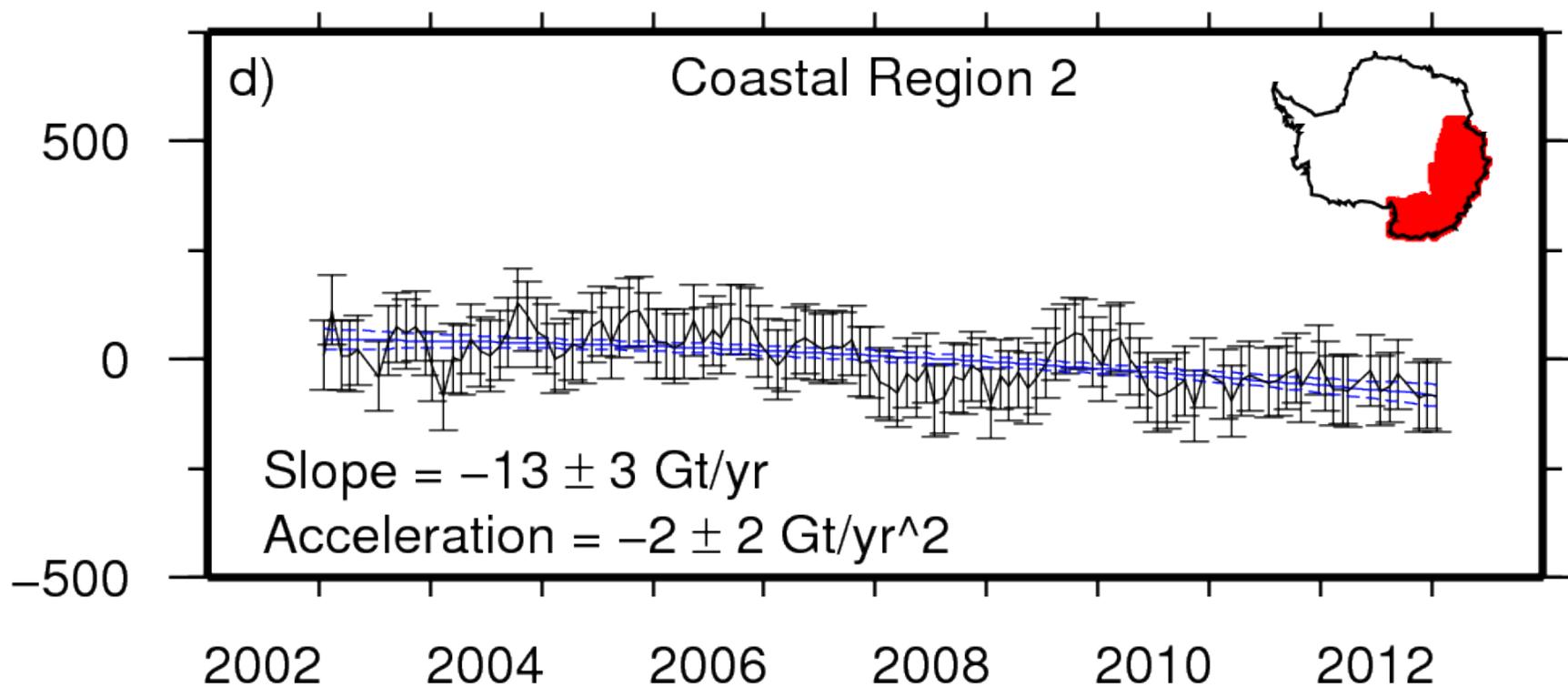
Using **spatiospectral localization techniques** and basis projection we recover subtle changes in Earth's gravitational and magnetic fields from noisy and incomplete satellite data.

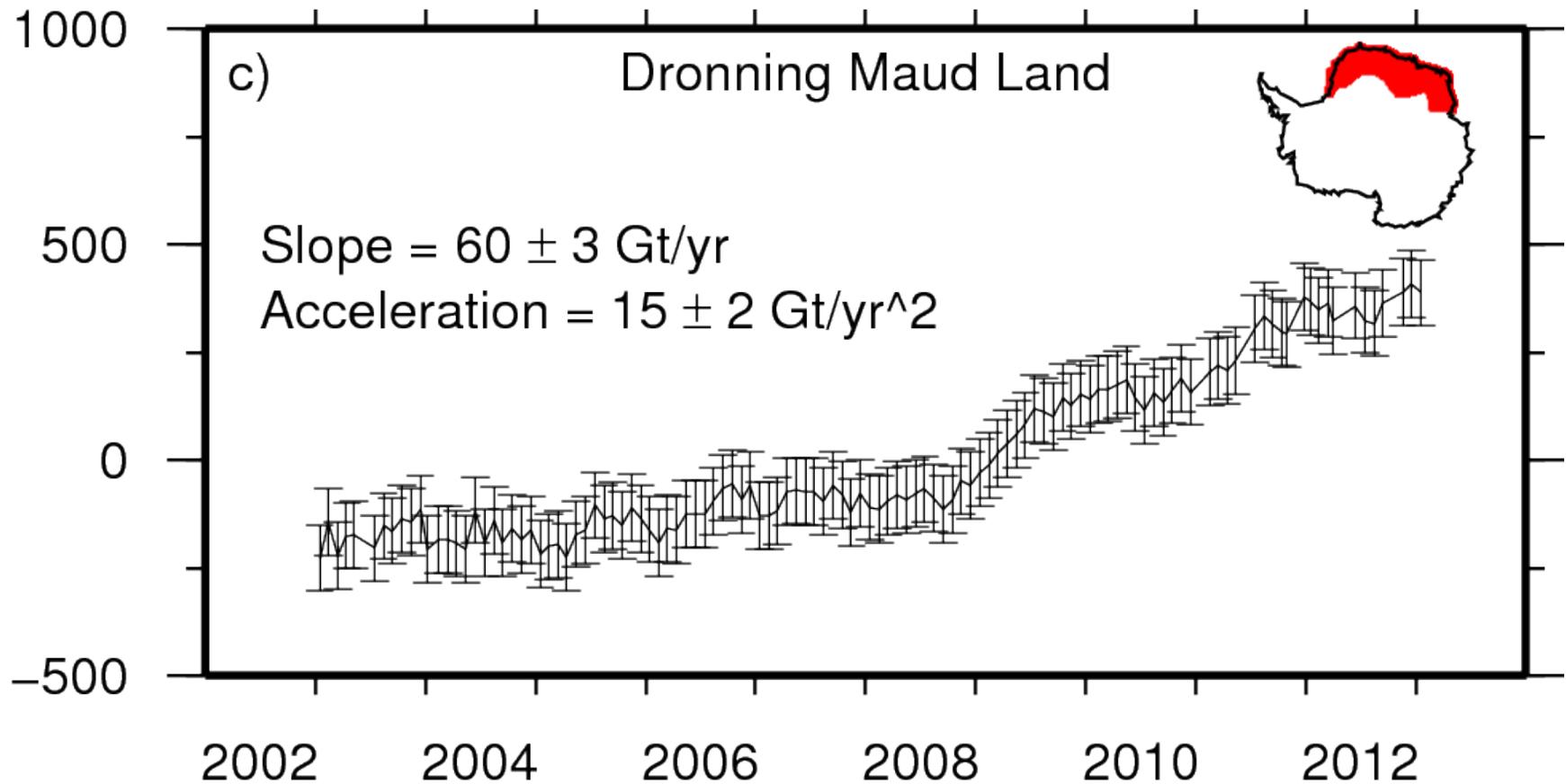
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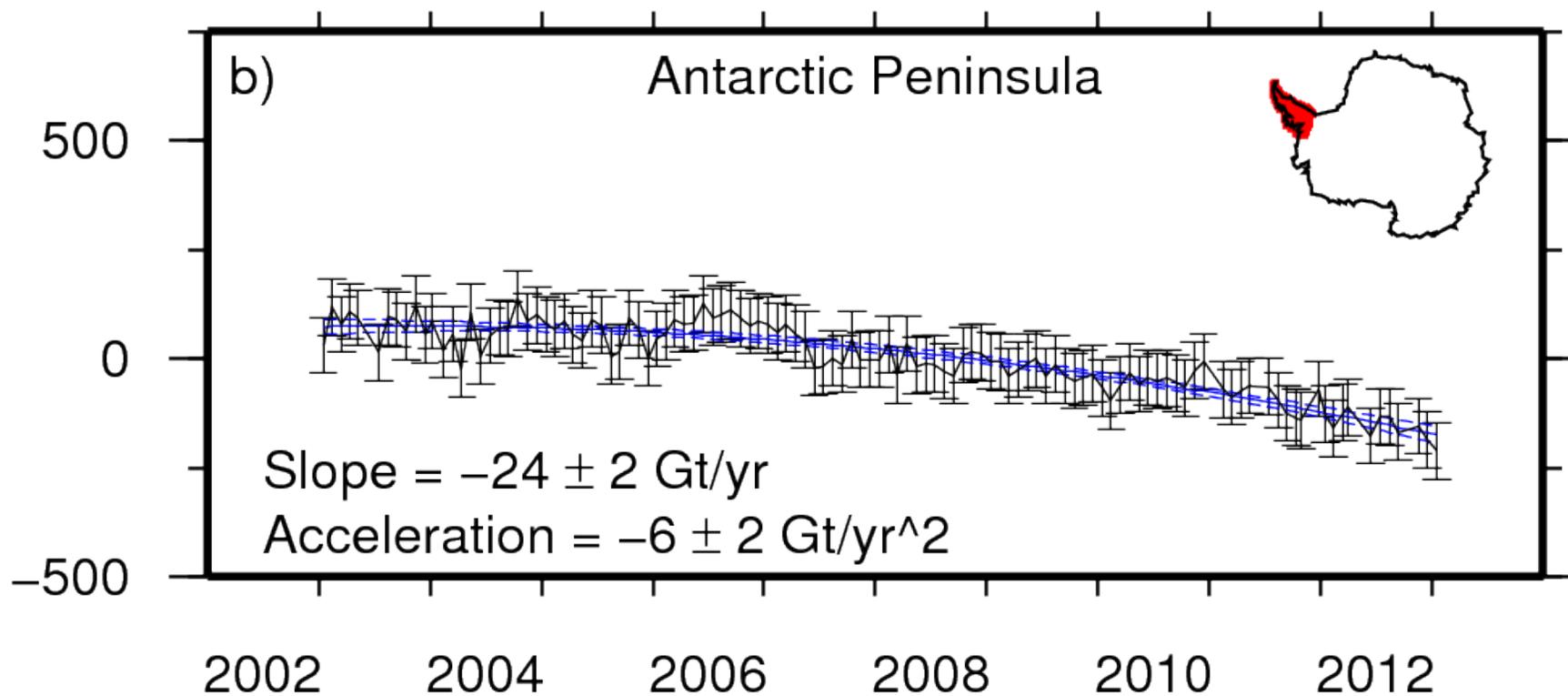
Using **adaptive sampling techniques** and **Gaussian process modelling** we can turn messy geological data into a coherent statistical model of the history of geophysical processes such as sea level change through time.











Ice mass loss 2002–2013

