

Homework problem set #4 : For the massive and/or tense.

1. You are about deduce the nature of the dynamical boundary condition for a somewhat more complicated kind of boundary, a so-called massive, tense boundary. A massive, tense boundary has a net mass density and is also under isotropic surface tension. A good example of such a boundary is a soap bubble which may be considered to be the boundary between the two continua inside and outside (both air).

Given an interface $\tilde{A}$ between two continua 1 and 2, let $\tilde{A}$ have a mass density μ gm/cm², and let its particles move with velocity $\underline{Q}$ and accelerations $\underline{a} = \frac{DQ}{Dt}$.

Suppose also that there is a force $\underline{f}_s$ dyne/cm² acting on $\tilde{A}$ (e.g. since it has mass there will be gravitational force in the Earth's field). Suppose finally that $\tilde{A}$ is under isotropic surface tension. By this we mean:

Let dC be any very short, nearly straight curve in $\tilde{A}$. Let

$\hat{c}$ be a unit vector tangent to dC (and hence to $\tilde{A}$), let $\hat{n}$ be

the unit normal to $\tilde{A}$ and let

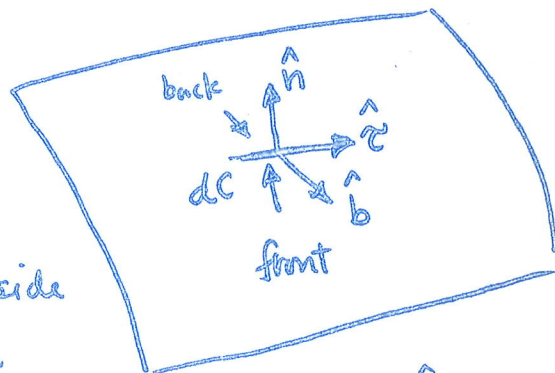
$\hat{b} = \hat{c} \times \hat{n}$. Then we assume that the

surface material in $\tilde{A}$ just in front (side

$\hat{b}$) of dC exerts on the surface material

just behind dC a force $\gamma \hat{b} dC$, where γ is independent of $\hat{b}$.

The theory can be worked out for anisotropic surface tension (one assumes only that the force is tangent to $\tilde{A}$ and proportional



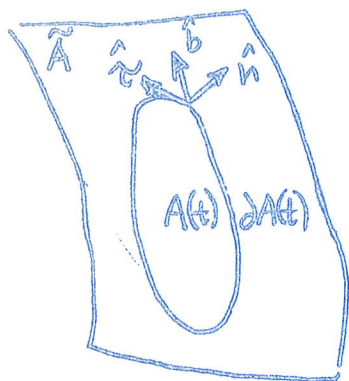
not true; should say: the boundary between soapy water and air.

to dC , permitting its magnitude and direction to depend on $\hat{r}$)

We shall not consider this case.

The number $\gamma(\underline{r}, t)$ is the surface tension in the surface at position $\underline{r}$ at time t .

Now let's apply Newton's second law of motion to a finite patch $A(t)$ on the surface $\tilde{A}$



$$\frac{d}{dt} \int_{A(t)} \mu \underline{Q} dA = \int_{A(t)} \hat{n} \cdot (\underline{T}_1 - \underline{T}_2) dA + \int_{A(t)} \underline{F}_S dA + \int_{\partial A(t)} \gamma \hat{b} dC$$

↑ this with $\hat{n}$ pointing into (1)

Now we need to express all terms in this equation as surface integrals over $A(t)$, so we can then apply the obvious extension of the vanishing integral theorem for surfaces.

(a) show that $\frac{d}{dt} \int_{A(t)} \mu \underline{Q} dA = \int_{A(t)} \mu \frac{DQ}{Dt}$

(hint: give μ and $\underline{Q}$ their Lagrangian descriptions, and transform variables to $A(0)$, the initial position of the patch)

Now consider the integral $\int_{\partial A(t)} \gamma \hat{b} dC$

(b) show that $\int_{\partial A(t)} \gamma \hat{b} dC = \epsilon_{ijk} \int_{\partial A(t)} (\gamma n_k \hat{x}_j) \cdot \hat{r} dC$ (easy)

For any fixed j, k this integral is in the form to which Stokes' theorem is applicable, except that the vector field $\gamma n_k \hat{x}_j$ is defined only on $\tilde{A}$, not in space. This prevents us from calculating $\nabla \times (\gamma n_k \hat{x}_j)$.

To circumvent this we use the following artifice. We simply extend the domain of definition of δ , defining δ above and below $\tilde{A}$ in any manner whatever (so long as $\nabla\delta$ is continuous).

What can we do about $\hat{n}$. Well, on $\tilde{A}$ if $\psi(x,t)=0$ is the equation of $\tilde{A}$, we know $\hat{n} = \nabla\psi/|\nabla\psi|$. We simply define $\hat{n}$ at points not on $\tilde{A}$ in the same way $\hat{n} = \nabla\psi/|\nabla\psi|$. Now we can calculate $\nabla \times (\delta \mathbf{n}_k \hat{x}_j)$. Pretty sly, huh?.

(c) now you may use Stokes theorem to show that

$$\int_{\partial A(t)} \delta \hat{b} dC = \int_{A(t)} [-\delta \hat{n} (\nabla \cdot \hat{n}) + (\nabla \delta - \hat{n} (\hat{n} \cdot \nabla \delta))] dA$$

Now we have everything tidily tucked away under a $\int_{\partial A(t)}$ sign, we apply the vanishing integral theorem

The differential form of Newton's law for a massive tense interface is $[\hat{n} \cdot \mathbf{T}]^\pm$

$$\mu \frac{DQ}{Dt} = \hat{n} \cdot (\underline{T}_1 - \underline{T}_2) + \underline{f}_S - \delta \hat{n} (\nabla \cdot \hat{n}) + [\nabla \delta - \hat{n} (\hat{n} \cdot \nabla \delta)] \quad (*)$$

This is the required dynamical boundary condition. Let's look at it. Look first at $[\nabla \delta - \hat{n} (\hat{n} \cdot \nabla \delta)]$. This quantity can be calculated by differentiating δ only in directions tangent to $\tilde{A}$ ($\nabla \delta - \hat{n} (\hat{n} \cdot \nabla \delta)$ is the $\perp$ projection of $\nabla \delta$ onto $\tilde{A}$). Thus the arbitrary way in which we extended the definition of δ above and below $\tilde{A}$ produces no arbitrariness in (*). If it did, we'd be in trouble

If (*) is to be of any use, $\nabla \cdot \hat{n}$ must be calculated

(d). Let $\psi(x,t)=0$ be the equation of $\tilde{A}$. Show that

$$\nabla \cdot \hat{n} = \partial n_i / \partial r_i = \frac{|\nabla \psi|^2 (\nabla^2 \psi) - \sum_{i,j} \frac{\partial \psi}{\partial r_i} \frac{\partial \psi}{\partial r_j} \left(\frac{\partial^2 \psi}{\partial r_i \partial r_j} \right)}{|\nabla \psi|^3}$$

(e) let $\tilde{A}$ be the surface of a sphere of radius a , center at origin ⁴
 $\Psi(\underline{x}) = (x_1)^2 + (x_2)^2 + (x_3)^2 - a^2$

Show that $\nabla \cdot \hat{n} = \frac{2}{a}$

It is a well-known fact in differential geometry that in general $\nabla \cdot \hat{n}$ is the sum of the two principal curvatures of $\tilde{A}$. The above result is a special case.

Specialize now to a surface on which $\mu=0$ (massless) and $\underline{f}_S=0$ (no "body" forces acting)

Furthermore let γ be constant on $\tilde{A}$ (no surface tension gradient)

Furthermore let the continua (1) and (2) have isotropic stress tensors $\underline{T}_{(1)} = -P_{(1)} \underline{I}$, $\underline{T}_{(2)} = -P_{(2)} \underline{I}$.

(f) Show that the b.c. reduces to

$$P_{(2)} - P_{(1)} = +\gamma \nabla \cdot \hat{n}$$

— this with $\hat{n}$ pointing into (1)

$$[p]^+ = -\gamma \nabla \cdot \hat{n}$$

$\hat{n}$ points to + side

(g) assume air and water have isotropic stress tensors

Find the pressure (in atmospheres) inside a raindrop

10^{-4} cm in diameter. Use $\gamma = 72$ dyne/cm for distilled H_2O

(h) If $\gamma = 24$ dyne/cm for soapy air water interface, how does the pressure inside a soap bubble depend on its radius?

(i) Find $\nabla \cdot \hat{n}$ on the surface of the ellipsoid $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$

Massive tense answers #4:

(a) $\frac{d}{dt} \int_{A(t)} \mu \underline{Q} dA$. Let u, v be a parameterization of $A(0)$

at time zero. As (u, v) runs over a certain region B in the u, v plane, the vector $\underline{r}_0(u, v)$ runs over the surface $A(0)$. At any later time t , the particle at $\underline{r}_0(u, v)$ has moved to a point $\underline{r}_t(u, v)$ on $A(t)$. Now $dA = \left| \frac{\partial \underline{r}}{\partial u} \times \frac{\partial \underline{r}}{\partial v} \right| du dv$ so

$$\int_{A(t)} \mu dA = \int_B \mu_t \left| \frac{\partial \underline{r}_t}{\partial u} \times \frac{\partial \underline{r}_t}{\partial v} \right| du dv. \text{ But then}$$

$$\int_{A(0)} \mu_0 dA_0 = \int_B \mu_0 \left| \frac{\partial \underline{r}_0}{\partial u} \times \frac{\partial \underline{r}_0}{\partial v} \right| du dv \text{ so by the vanishing integral}$$

theorem $\mu_0 \left| \frac{\partial \underline{r}_0}{\partial u} \times \frac{\partial \underline{r}_0}{\partial v} \right| = \mu_t \left| \frac{\partial \underline{r}_t}{\partial u} \times \frac{\partial \underline{r}_t}{\partial v} \right|$ (conservation of surface mass)

Then $\int_{A(t)} \mu \underline{Q} dA = \int_B \mu_t \left| \frac{\partial \underline{r}_t}{\partial u} \times \frac{\partial \underline{r}_t}{\partial v} \right| \underline{Q} du dv = \int_B \mu_0 \left| \frac{\partial \underline{r}_0}{\partial u} \times \frac{\partial \underline{r}_0}{\partial v} \right| \underline{Q} du dv$

Hence $\frac{d}{dt} \int_{A(t)} \mu \underline{Q} dA = \frac{d}{dt} \int_B \mu_0 \left| \frac{\partial \underline{r}_0}{\partial u} \times \frac{\partial \underline{r}_0}{\partial v} \right| \underline{Q} du dv = \int_B \mu_0 \left| \frac{\partial \underline{r}_0}{\partial u} \times \frac{\partial \underline{r}_0}{\partial v} \right| \frac{\partial \underline{Q}}{\partial t} du dv$

Here $\frac{\partial \underline{Q}}{\partial t}$ means the derivative of $\underline{Q}$ holding u, v fixed, i.e. holding the particle fixed. Thus $\frac{\partial \underline{Q}}{\partial t} \equiv \frac{D \underline{Q}}{Dt}$, and

$$\begin{aligned} \frac{d}{dt} \int_{A(t)} \mu \underline{Q} dA &= \int_B \mu_0 \left| \frac{\partial \underline{r}_0}{\partial u} \times \frac{\partial \underline{r}_0}{\partial v} \right| \frac{D \underline{Q}}{Dt} du dv = \int_B \mu_t \left| \frac{\partial \underline{r}_t}{\partial u} \times \frac{\partial \underline{r}_t}{\partial v} \right| \frac{D \underline{Q}}{Dt} du dv \\ &= \int_{A(t)} \mu D_t \underline{Q} dA \end{aligned}$$

(b) $\hat{b} = \hat{\tau} \times \hat{n}$ so $b_i = \epsilon_{ijk} \tau_j n_k = (\epsilon_{ijk} n_k \hat{x}_j) \cdot \hat{\tau}$ Thus

$$\int_{\partial A} x^i b_i dC = \epsilon_{ijk} \int_{\partial A} (x^i n_k \hat{x}_j) \cdot \hat{\tau} dC$$

(c)

$$\begin{aligned}\nabla \times (\delta n_k \hat{x}_j) &= -\hat{x}_j \times \nabla (\delta n_k) = -\hat{x}_j \times \hat{x}_\ell \partial_\ell (\delta n_k) \\ &= -\epsilon_{j\ell m} \hat{x}_m \partial_\ell (\delta n_k)\end{aligned}$$

$$\text{Thus } \int_{\partial A} \delta b_i d\mathbf{c} = \int_A \hat{n} \cdot [\nabla \times (\delta n_k \hat{x}_j)] dA \quad (\text{Stokes})$$

$$= -\epsilon_{ijk} \epsilon_{j\ell m} \int_A \hat{n} \cdot \hat{x}_m \partial_\ell (\delta n_k) dA = - \int_A (\delta_{im} \delta_{k\ell} - \delta_{i\ell} \delta_{km}) \hat{n}^m \partial_\ell (\delta n_k) dA$$

The integrand is $n_i \partial_k (\delta n_k) - n_k \partial_i (\delta n_k)$

$$= \delta n_i \partial_k n_k + n_i (n_k \partial_k \delta) - n_k n_k \partial_i \delta - \delta n_k \partial_i n_k$$

But $n_k n_k = 1$ so $n_k \partial_i n_k = 0$

$$\int_{\partial A} \delta b_i d\mathbf{c} = - \int_A [\delta n_i (\nabla \cdot \hat{n}) + n_i (\hat{n} \cdot \nabla \delta) - \partial_i \delta] dA$$

$$\int_{\partial A} \delta b_i d\mathbf{c} = \int_A [-\delta \hat{n} (\nabla \cdot \hat{n}) + \underbrace{(\nabla \delta - \hat{n} (\hat{n} \cdot \nabla \delta))}_{\text{the so-called surface gradient}}] dA$$

$$(d) \quad \hat{n}_i = \frac{\nabla \psi}{|\nabla \psi|} = \frac{\partial \psi}{\partial r_i} \left(\frac{\partial \psi}{\partial r_j} \frac{\partial \psi}{\partial r_j} \right)^{-1/2}$$

$$\nabla \cdot \hat{n} = \partial_i \hat{n}_i = \frac{|\nabla \psi|^2 \nabla^2 \psi - \nabla \psi \cdot \nabla \nabla^2 \psi}{|\nabla \psi|^3}$$

$$(e) \quad |\nabla \psi| = 2a$$

$$\nabla^2 \psi = 6$$

$$\nabla \cdot \hat{n} = \frac{2}{a}$$

$$\nabla \psi \cdot \nabla \nabla^2 \psi = 8a^2 \quad \hat{n} \text{ pointing into } \langle \rangle.$$

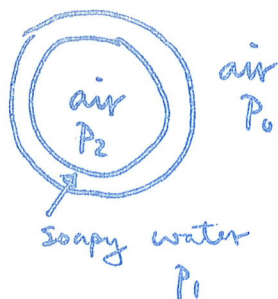
$$(f) \quad \text{easy} \quad P_{\text{out}} - P_{\text{in}} = +\delta (\nabla \cdot \hat{n})$$

$$(g) \quad \text{radius} = \frac{1}{2} \cdot 10^{-4} \text{ cm}, \quad \frac{2}{a} = 4 \cdot 10^4 \text{ cm}^{-1}$$

$$P_{\text{in}} - P_{\text{out}} = (4 \cdot 10^4) (72) = 2.9 \cdot 10^6 \text{ dyne/cm}^2 = 2.9 \text{ atm.}$$

$$\text{if } P_{\text{out}} = 1 \text{ atm} \quad P_{\text{in}} = 3.9 \text{ atm.}$$

(h)



$$P_1 - P_0 = \frac{2}{a} \gamma$$

$$P_2 - P_1 = \frac{2}{a} \gamma$$

$$\boxed{P_2 - P_0 = \frac{4}{a} \gamma}$$

$$(i) \quad \psi = \frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} - 1$$

$$\nabla \psi = \frac{2x}{a^2} \hat{x} + \frac{2y}{b^2} \hat{y} + \frac{2z}{c^2} \hat{z}$$

$$\nabla^2 \psi = \frac{2}{a^2} + \frac{2}{b^2} + \frac{2}{c^2}$$

$$\underline{\nabla} \psi \cdot \underline{\nabla} \psi = \left(\frac{2x}{a^2}, \frac{2y}{b^2}, \frac{2z}{c^2} \right) \begin{pmatrix} \frac{2}{a^2} & 0 & 0 \\ 0 & \frac{2}{b^2} & 0 \\ 0 & 0 & \frac{2}{c^2} \end{pmatrix} \begin{pmatrix} \frac{2x}{a^2} \\ \frac{2y}{b^2} \\ \frac{2z}{c^2} \end{pmatrix}$$

$$= 8 \left(\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4} \right)$$

$$\nabla \cdot \hat{n} = \frac{\left(\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4} \right) \left(\frac{1}{a^2} + \frac{1}{b^2} + \frac{1}{c^2} \right) - \left(\frac{x^2}{a^6} + \frac{y^2}{b^6} + \frac{z^2}{c^6} \right)}{\left(\frac{x^2}{a^4} + \frac{y^2}{b^4} + \frac{z^2}{c^4} \right)^{3/2}}$$

Not all problems have pretty answers.